

FINITE TIME ANALYTICITY FOR THE TWO- AND THREE-DIMENSIONAL RAYLEIGH-TAYLOR INSTABILITY

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ABSTRACT. The Rayleigh-Taylor instability refers to the dynamics of the interface between two ideal irrotational fluids of different densities superposed one over the other and in relative motion. The well-posedness of this problem is considered for two- and three-dimensional flows in the entire space and in the presence of a horizontal bottom. In the entire space, finite time analyticity of the interface is proven when the initial interface has sufficiently small gradients and is flat at infinity. In the presence of a horizontal bottom, the initial interface corrugations has also to be small initially but it is not required to vanish at infinity.

1. Introduction. A fluid of constant density ρ_- and horizontal velocity u_- superposed over a fluid of constant density ρ_+ and velocity u_+ parallel to u_- corresponds to a stationary solution to the Euler equation. But this configuration is linearly unstable for any perturbation of the interface of wave number k in the direction of the flow with modulus [1]

$$|k| > \frac{4\alpha}{1 - \alpha^2} \frac{g}{(u_+ - u_-)^2}.$$

The coefficient $\alpha = (\rho_+ - \rho_-)/(\rho_+ + \rho_-)$ is generally called the Atwood ratio; g denotes the gravity field. When the two fluids have the same density ($\alpha = 0$), the problem is often referred to as the Kelvin-Helmholz instability. In this case, small corrugation of any wave number is amplified exponentially. As a consequence, the linear problem is well posed only for an analytic initial interface, and thus generally only during a finite time [2]. In contrast, for the water wave problem where the lower fluid is much denser than the upper one ($\alpha = 1$), the interface is linearly stable, suggesting that nonanalytic initial free surfaces may be considered.

Well-posedness for the nonlinear water waves has been investigated by many authors. Existence during a finite time has been established in spaces of analytic functions [3–6], and also in Sobolev spaces and Hölder spaces [7–9]. They either transform the fluid region on a simple domain by means of a conformal mapping (two-dimensional problem) or follow the evolution of the free surface in Lagrangian coordinates. The Rayleigh-Taylor problem ($\alpha \neq 1$) in two-dimensions has been considered in [10] where a finite time analyticity result is presented. The proof, which in places is only sketched, uses scales of spaces of analytic functions à la Ovsjannikov [11]. The present paper also deals with the well-posedness of the Rayleigh-Taylor problem and extends to it an analysis previously done for the Kelvin-Helmholtz

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problem [12]. Both two- and three-dimensional flows are considered and a class of analytic initial conditions larger than in [10] is permitted. In addition, periodicity is not required. In §§2 and 3, we derive for two- and three-dimensional flows, a close system of equations for the interface and the vorticity density. This is done by writing the momentum equation for inhomogeneous flow in the sense of distributions. When the densities of the two fluids are different ($\alpha \neq 0$), the equation for the vorticity density is of Fredholm type. In §4, we adapt to this problem Nishida's formulation [13, 14] of an abstract Cauchy-Kowalevski theorem in scales of Banach spaces [11, 15]. In §5, this theorem is used to prove analyticity during a finite time for the Rayleigh-Taylor problem in the entire space, under the condition that the interface gradients are sufficiently small initially. When the interface is not periodic, it is assumed to be flat at infinity. The effect of a horizontal bottom is considered in §6. In this case, the initial corrugation has also to be sufficiently small but is not required to vanish at infinity. This is due to a faster decay of the Green function of the Poisson equation at large distances. Finally, a few open problems are discussed in §7.

2. Equations of motion of the interface in two dimensions. We consider a fluid of density ρ_- superposed on a fluid of density ρ_+ . The flow is irrotational in each of the domains where the fluid is homogeneous but a velocity discontinuity at the interface is permitted. The momentum equation reads:

$$(2.1) \quad \begin{aligned} (a) \quad & \frac{\partial}{\partial t}(\rho u) + \sum_i \frac{\partial}{\partial x_i}(\rho u_i u) + \nabla p - \rho \vec{g} = 0, \\ (b) \quad & \operatorname{div} u = 0 \end{aligned}$$

where $\vec{g} = (0, -g)$ is the gravity field.

The jump conditions across the interface are easily derived from the equation satisfied by $\operatorname{Curl}(\rho u)$ in the sense of distribution. We denote by $\varphi(\vec{r}, t)$ a vectorial test-function perpendicular to the plane of the flow. It will be sometimes identified with its unique component. We assume that φ has a compact support which does not intersect the possible bottom. We have

$$(2.2) \quad \begin{aligned} (a) \quad & \rho u \operatorname{Curl} \frac{\partial \varphi}{\partial t} d\vec{r} dt + \int \rho u_i u \operatorname{Curl} \frac{\partial \varphi}{\partial x_i} d\vec{r} dt - \vec{g} \int \rho \operatorname{Curl} \varphi d\vec{r} dt = 0, \\ (b) \quad & \int (u \cdot \nabla) \varphi d\vec{r} = 0. \end{aligned}$$

For simplicity, we shall consider in this section the case of a two-dimensional flow. The three-dimensional problem is considered in §3.

The interface is represented by the equation

$$(2.3) \quad r = r(\lambda, t), \quad \lambda \in R,$$

or when cartesian coordinates are used

$$(2.4) \quad x = x(\lambda, t), \quad y = y(\lambda, t).$$

$N = (-y_\lambda, x_\lambda)$ is a vector normal to the interface. n and τ are normal and tangent unit vectors, respectively. The vorticity density $\Omega(\lambda, t)$ on the interface is a vector

perpendicular to the plane of the flow defined as

$$(2.5) \quad \int \psi(r) \operatorname{Curl} u(r, t) dr = \int \psi(r(\lambda, t)) \Omega(\lambda, t) d\lambda,$$

where $\psi(r)$ is a scalar test function.

The velocity in a point exterior to the interface is given by the Biot-Savart formula

$$u(r, t) = \int \nabla G(r, r(\lambda', t)) \wedge \Omega(\lambda', t) d\lambda',$$

where G is the Green function of the Laplace operator in the domain. In the absence of boundaries and when the velocity vanishes at infinity,

$$G(r, r') = -\frac{1}{2\pi} \ln \sqrt{(x - x')^2 + (y - y')^2}.$$

in the presence of a horizontal bottom,

$$G(r, r') = -\frac{1}{2\pi} \ln \sqrt{\frac{(x - x')^2 + (y - y')^2}{(x - x')^2 + (y + y')^2}}.$$

If the interface is sufficiently smooth, the velocity u has limits $u^\pm(\lambda, t)$ when r tends in an arbitrary way from one or the other side to a point $r(\lambda, t)$ of the interface. In addition,

$$(2.6) \quad V(\lambda, t) \stackrel{\text{def}}{=} \frac{u^+ + u^-}{2}(\lambda, t) = \oint \nabla G(r(\lambda, t), r(\lambda', t)) \wedge \Omega(\lambda', t) d\lambda',$$

where $\oint$ indicates that the integral is taken in the sense of Cauchy principal value.

We rewrite each integral in (2.2) and (2.5) as the sums of integrals in each of the two subdomains separated by the interface, and apply the Green formula to the different terms. In each of these domains, the flow is homogeneous and irrotational and the Euler equation is satisfied in a classical sense. The only remaining contributions thus come from the interface. We denote by $[f] = f^+ - f^-$ the jump across the interface of a function defined on one and the other side. (2.2)(b) and (2.5) imply

$$(2.7) \quad \begin{aligned} (a) \quad & [u] \cdot N = 0, \\ (b) \quad & [u] \wedge N = \Omega \end{aligned}$$

and (2.2)(a) is rewritten in the form

$$(2.8) \quad \begin{aligned} & \int ([\rho u] \wedge N) \cdot \frac{\partial \varphi}{\partial t} dt d\lambda + \int ([\rho u_i u] \wedge N) \cdot \frac{\partial \varphi}{\partial x_i} d\lambda dt \\ & + \int [\operatorname{Curl}(\rho u_i u)] \cdot N_i \varphi d\lambda dt - [\rho] \int (g \wedge N) \cdot \varphi d\lambda dt = 0. \end{aligned}$$

In the first term of (2.8), we make the replacement

$$(2.9) \quad \frac{\partial \varphi}{\partial t}(r(\lambda, t), t) = \frac{d\varphi}{dt}(r(\lambda, t), t) - \left(\frac{\partial r}{\partial t} \cdot \tau \right) \frac{\partial \varphi}{\partial \tau} - \left(\frac{\partial r}{\partial t} \cdot n \right) \frac{\partial \varphi}{\partial n},$$

where $\partial/\partial\tau = (1/\|N\|)\partial/\partial\lambda$. We rewrite the second term of (2.8) in the form

$$(2.10) \quad \int ([\rho u_i u] \wedge N) \cdot \frac{\partial \varphi}{\partial x_i} d\lambda dt = \int (V \cdot n)([\rho u] \wedge N) \cdot \frac{\partial \varphi}{\partial n} d\lambda dt \\ + \int \left\{ (V \cdot \tau)[\rho u] \wedge N + ([u] \cdot \tau) \frac{(\rho u)^+ + (\rho u)^-}{2} \wedge N \right\} \cdot \frac{\partial \varphi}{\partial \tau} d\lambda dt.$$

In the third term, we use

$$[\text{Curl}(\rho u_i u)]N_i = N_i[\nabla u_i \wedge \rho u] \\ = \left(n \cdot \frac{\partial V}{\partial \lambda} \right) [\rho u] \cdot n + \left(\tau \cdot \frac{\partial V}{\partial \lambda} \right) [\rho u] \cdot \tau \\ + [u] \frac{(\rho u)^+ + (\rho u)^-}{2} \cdot n + \frac{\partial}{\partial \lambda} ([u] \cdot \tau) \frac{(\rho u)^+ + (\rho u)^-}{2} \cdot \tau.$$

After integration by parts, (2.8) becomes

$$(2.12) \quad \int \left\{ -\frac{\partial}{\partial t} ([\rho u] \wedge N) + \frac{\partial}{\partial \lambda} \left(\left(\frac{\partial r}{\partial t} - V \right) \cdot \tau [\rho u] \wedge n \right) \right. \\ - [u] \cdot \tau \frac{\partial}{\partial \lambda} \left(\frac{(\rho u)^+ + (\rho u)^-}{2} \cdot \tau \right) + \left(n \cdot \frac{\partial V}{\partial \lambda} \right) [\rho u] \cdot n \\ + \left(\tau \cdot \frac{\partial V}{\partial \lambda} \right) [\rho u] \cdot \tau + ([u] \cdot \tau) \frac{(\rho u)^+ + (\rho u)^-}{2} \cdot n + [\rho]g \wedge N \left. \right\} \cdot \varphi \\ + \left\{ \left(V - \frac{\partial r}{\partial t} \right) \cdot n [\rho u] \wedge N \right\} \cdot \frac{\partial \varphi}{\partial n} = 0,$$

where the vectors perpendicular to the plane of the flow are identified with their unique component.

(2.12) is satisfied for any test function φ ; the coefficients of φ and $\partial\varphi/\partial n$ in (2.12) thus vanish. Expressing $(\rho u)^+ \pm (\rho u)^-$ in terms of V and Ω one finally obtains

PROPOSITION 2.1. *If during a period of time, the interface between two two-dimensional ideal fluids of different densities superposed one over the other remains a smooth curve $\Gamma(t) = \{r = r(\lambda, t), \lambda \in R\}$ with a vorticity density $\Omega(\lambda, t)$, we have*

$$(2.13) \quad (a) \quad (r_t - V) \cdot n = 0, \\ (b) \quad \frac{\partial}{\partial t} \{ \Omega + \alpha(V \cdot r_\lambda) \} + \frac{\partial}{\partial \lambda} \left\{ \frac{1}{|r_\lambda|^2} ((V - r_t) \cdot r_\lambda) \left(\frac{\Omega}{2} + \alpha(V \cdot r_\lambda) \right) \right\} \\ - \alpha \frac{\partial}{\partial \lambda} \left\{ \frac{\Omega^2}{8|r_\lambda|^2} - \frac{|V|^2}{2} \right\} + \alpha g y_\lambda = 0.$$

In (2.13) subscripts denote partial derivatives and n is a unit vector normal to Γ . If no boundary is present and the fluids are at rest at infinity

$$(2.14) \quad V(\lambda, t) = \frac{1}{2\pi} \int \frac{r(\lambda, t) - r(\lambda', t)}{|r(\lambda, t) - r(\lambda', t)|^2} \wedge \Omega(\lambda', t) d\lambda'.$$

In the presence of a horizontal bottom ($r = (x, y)$, $\bar{r} = (x, -y)$)

$$(2.15) \quad V(\lambda, t) = \frac{1}{2\pi} \int \left(\frac{r(\lambda, t) - r(\lambda', t)}{|r(\lambda, t) - r(\lambda', t)|^2} - \frac{r(\lambda, t) - \bar{r}(\lambda', t)}{|r(\lambda, t) - \bar{r}(\lambda', t)|^2} \right) \wedge \Omega(\lambda', t) d\lambda'.$$

If ρ^- and ρ^+ are the densities of the upper and lower fluids, respectively, $\alpha = (\rho^+ - \rho^-)/(\rho^+ + \rho^-)$.

The system (2.13), (2.14) simplifies when the interface can be resolved in the form $y = y(x, t)$. It becomes

$$(2.16) \quad \begin{aligned} (a) \quad & y_t - V_2 + y_x V_1 = 0, \\ (b) \quad & \frac{\partial}{\partial t} \left\{ \frac{\Omega}{2} + \alpha(V_1 + y_x V_2) \right\} + \frac{\partial}{\partial x} \left\{ V_1 \left(\frac{\Omega}{2} + \alpha(V_1 + y_x V_2) \right) \right. \\ & \left. + \alpha \left(\frac{\Omega^2}{8(1 + y_x^2)} - \frac{|V|^2}{2} + gy \right) \right\} = 0. \end{aligned}$$

In the entire plane

$$(2.17) \quad \begin{aligned} V_1(x, t) &= -\frac{1}{2\pi} \oint \frac{y(x, t) - y(x', t)}{(x - x')^2 + (y(x, t) - y(x', t))^2} \Omega(x', t) dx', \\ V_2(x, t) &= \frac{1}{2\pi} \oint \frac{x - x'}{(x - x')^2 + (y(x, t) - y(x', t))^2} \Omega(x', t) dx'; \end{aligned}$$

in the presence of a horizontal bottom,

$$(2.18) \quad \begin{aligned} V_1(x, t) &= -\frac{1}{2\pi} \int \left(\frac{y(x, t) - y(x', t)}{(x - x')^2 + (y(x, t) - y(x', t))^2} \right. \\ & \quad \left. - \frac{y(x, t) + y(x', t)}{(x - x')^2 + (y(x, t) + y(x', t))^2} \right) \Omega(x', t) dx', \\ V_2(x, t) &= \frac{1}{2\pi} \int \left(\frac{x - x'}{(x - x')^2 + (y(x, t) - y(x', t))^2} \right. \\ & \quad \left. - \frac{x - x'}{(x - x')^2 + (y(x, t) + y(x', t))^2} \right) \Omega(x', t) dx'. \end{aligned}$$

Computing the time derivative in (2.15)(b) and using (2.15)(a), one obtains

PROPOSITION 2.2. *When the Rayleigh-Taylor problem is considered in R^2 and the interface can be resolved in the form $y = y(x, t)$, the equations of motion become*

$$(2.19) \quad \begin{aligned} (a) \quad & y_t - V_2 + y_x V_1 = 0, \\ (b) \quad & \frac{1}{2} \frac{\partial \Omega}{\partial t} - \alpha A\{y\} \frac{\partial \Omega}{\partial t} + \frac{\partial F}{\partial x} = 0, \end{aligned}$$

where

$$(2.20) \quad A\{y\} \frac{\partial \Omega}{\partial t}(x) = \int \frac{y(x, t) - y(x', t) - (x - x')y_x(x, t)}{(x - x')^2 + (y(x, t) - y(x', t))^2} \frac{\partial \Omega}{\partial t}(x', t) dx'$$

and

$$(2.21) \quad \begin{aligned} F(x, t) &= \frac{1}{2} V_1(x, t) \Omega(x, t) + \alpha \left(\frac{|V(x, t)|^2}{2} + \frac{\Omega^2(x, t)}{8(1 + y_x^2(x, t))} \right) \\ & \quad + \alpha \int \frac{(x - x') \Omega(x', t) (V_2(x', t) - y_x(x, t) V_1(x', t))}{(x - x')^2 + (y(x, t) - y(x', t))^2} dx' + \alpha gy = 0. \end{aligned}$$

V_1 and V_2 are defined in (2.17).

When a horizontal bottom is present, the equation for the vorticity density reads

$$(2.22) \quad \frac{\partial \Omega}{\partial t} + B\{y\} \frac{\partial \Omega}{\partial t} = S\{\Omega, y\}$$

with

$$(2.23) \quad \begin{aligned} S\{\Omega, y\} = & -\frac{\partial}{\partial x} \left(V_1 \frac{\Omega}{2} + \alpha \frac{|V|^2}{2} + \frac{\alpha}{8} \frac{\Omega^2}{1+y_x^2} + \alpha g y \right) \\ & + \frac{1}{2\pi} \frac{\partial}{\partial x} \int (V_2(x') - y_x(x') V_1(x')) \left(\frac{x-x'}{(x-x')^2 + (y(x,t) - y(x',t))^2} \right) \\ & - \left(\frac{x-x'}{(x-x')^2 + (y(x,t) + y(x',t))^2} \right) \Omega(x',t) dx' \end{aligned}$$

and

$$(2.24) \quad \begin{aligned} B\{y\} \frac{\partial \Omega}{\partial t} = & \frac{\alpha}{2\pi} \int \left(\frac{y(x) + y(x') - y_x(x)(x-x')}{(x-x')^2 + (y(x) + y(x'))^2} \right. \\ & \left. - \frac{y(x) - y(x') - y_x(x)(x-x')}{(x-x')^2 + (y(x) - y(x'))^2} \right) \frac{\partial \Omega}{\partial t}(x') dx'. \end{aligned}$$

Let us assume that $y(x, t)$ fluctuates around some mean value h . To isolate the linear contribution in the right-hand side of (2.24) we write

$$(2.25) \quad y(x, t) = h + \eta(x, t).$$

(2.22) becomes

$$(2.26) \quad \frac{\partial \Omega}{\partial t} + \int \frac{2h}{(x-x')^2 + 4h^2} \frac{\partial \Omega}{\partial t}(x') dx' = -C_h\{\eta\} \frac{\partial \Omega}{\partial t} + S\{\Omega, y\}$$

with

$$(2.27) \quad C_h\{\eta\} \frac{\partial \Omega}{\partial t} = B\{y\} \frac{\partial \Omega}{\partial t} - \int \frac{2h}{(x-x')^2 + 4h^2} \frac{\partial \Omega}{\partial t}(x') dx'.$$

The linear operator acting on $\partial \Omega / \partial t$ in the left-hand side of (2.26) is easily inverted by taking the Fourier transform of the equation. We finally obtain

PROPOSITION 2.3. *When the Rayleigh-Taylor problem is considered in the half-plane $y > 0$, and the interface can be resolved in the form $y = y(x, t) \equiv h + \eta(x, t)$, the equations of motion read*

$$(2.28) \quad \begin{aligned} (a) \quad & \eta_t - V_2 + \eta_x V_1 = 0, \\ (b) \quad & \frac{\partial \Omega}{\partial t} + A\{\eta\} \frac{\partial \Omega}{\partial t} = F\{\Omega, \eta\} \end{aligned}$$

with

$$(2.29) \quad A\{\eta\} \frac{\partial \Omega}{\partial t} = C_h\{\eta\} \frac{\partial \Omega}{\partial t} + \int \mathcal{G}(x-x') \left(C_h\{\eta\} \frac{\partial \Omega}{\partial t}(x') \right) dx',$$

$$(2.30) \quad F\{\Omega, \eta\} = S\{\Omega, y\} + \int \mathcal{G}(x-x') S\{\Omega, y\}(x') dx'.$$

The kernel $\mathcal{G}$ is given by

$$(2.31) \quad \mathcal{G}(x) = \int_{-\infty}^{+\infty} e^{-ikx} \frac{\alpha e^{-2h|k|}}{1 + \alpha e^{-2h|k|}} dk,$$

and thus decay like $|x|^{-2}$ when $x \rightarrow \pm\infty$. V_1 and V_2 are defined in (2.17) with $y = h + \eta$; C_h and S are given in (2.27) and (2.22).

3. Equations of motion of the interface in three dimensions. The interface is represented by the equation $\{\vec{r} = r(\vec{\lambda}, t), \vec{\lambda} = (\lambda_1, \lambda_2) \in R^2\}$. The vorticity density $\Omega(\vec{\lambda}, t)$ is defined by

$$(3.1) \quad \int \varphi(\vec{r}) \text{Curl } u(\vec{r}, t) d\vec{r} = \oint \varphi(r(\vec{\lambda}, t)) \Omega(\vec{\lambda}, t) d\vec{\lambda},$$

where φ is a test function. Like in dimension 2, when the interface is sufficiently smooth, we have

$$(3.2) \quad V\{\vec{\lambda}, t\} = \frac{u^+ + u^-}{2}(\lambda, t) = - \int \nabla G(\vec{r}(\vec{\lambda}, t), \vec{r}(\vec{\lambda}', t)) \wedge \Omega(\vec{\lambda}', t) d\vec{\lambda}',$$

where $u^\pm$ are the limits of the velocity $u(\vec{r}, t)$ when $\vec{r}$ tends from one or the other side to a point $\vec{r}(\vec{\lambda}, t)$ of the interface and G is the Green function of the Laplace operator. When the problem is considered in R^3 ,

$$(3.3) \quad G(\vec{r}, \vec{r}') = \frac{1}{4\pi} \frac{1}{|\vec{r} - \vec{r}'|}.$$

When it is considered in half a space,

$$(3.4) \quad G(\vec{r}, \vec{r}') = \frac{1}{4\pi} \left(\frac{1}{|\vec{r} - \vec{r}'|} - \frac{1}{|\vec{r} - \vec{r}'^*|} \right)$$

with $\vec{r} = (x_1, x_2, z)$ and $\vec{r}^* = (x_1, x_2, -z)$. a normal vector N to the interface is $N = \partial r / \partial \lambda_1 \wedge \partial r / \partial \lambda_2$. Using a Green' formula, (2.2) is rewritten as

$$(3.5) \quad \begin{aligned} & \int ([\rho u] \wedge N) \cdot \frac{\partial \varphi}{\partial t} d\vec{\lambda} dt + \int ([\rho u_i u] \wedge N) \cdot \frac{\partial \varphi}{\partial x_i} d\vec{\lambda} dt \\ & + \int [\text{Curl}(\rho u_i u)] \cdot (N_i \varphi) d\vec{\lambda} dt + [\rho] \int (g \wedge N) \cdot \varphi d\vec{\lambda} dt = 0. \end{aligned}$$

Proceeding as in [10], we obtain the following system of equations:

(3.6)

$$(a) \quad (r_t - V) \cdot N = 0,$$

$$(b) \quad - \frac{\partial}{\partial t} ([\rho u] \wedge N)$$

$$+ \sum_{j=1}^2 (-1)^{j+1} \frac{\partial}{\partial \lambda_j} \left\{ \frac{[\rho u] \wedge N}{\|N\|^2} \left(\frac{\partial r}{\partial t}, \frac{\partial r}{\partial \lambda_j}, N \right) - \frac{1}{\|N\|^2} \left(\frac{\partial r}{\partial \lambda_j} \wedge N \right)_i [\rho u_i u] \right\}$$

$$+ [\nabla u_i \wedge \rho u] N_i + \alpha \vec{g} \wedge N = 0.$$

In (3.6)(b), the subscript $\tilde{j}$ is 2 if $j = 1$ and 1 if $j = 2$; (a, b, c) denotes the triple scalar product $a \cdot (b \wedge c)$. Furthermore,

$$(3.7) \quad \frac{1}{\|N\|^2} \left(\frac{\partial r}{\partial \lambda_j} \wedge N \right)_i [\rho u_i u] \wedge N = \frac{1}{\|N\|^2} \left(V, \frac{\partial r}{\partial \lambda_j}, N \right) [\rho u] \wedge N \\ - \left([u] \wedge \frac{\partial r}{\partial \lambda_j} \right) \wedge \frac{(\rho u)^+ + (\rho u)^-}{2}$$

and [10]

$$(3.8) \quad [\nabla u_i \wedge \rho u] = \|N\| \left(\left[\frac{\partial u}{\partial n} \right] \wedge \frac{(\partial u)^+ + (\rho u)^-}{2} + \frac{\partial V}{\partial n} \wedge [\rho u] \right) \\ = \sum_{j=1}^2 (-1)^{j+1} \left\{ \frac{\partial}{\partial \lambda_j} \left(\frac{\partial r}{\partial \lambda_{\tilde{j}}} \wedge [u] \right) \wedge \frac{(\rho u)^+ + (\rho u)^-}{2} \right. \\ \left. + \left(\frac{\partial r}{\partial \lambda_{\tilde{j}}} \wedge \frac{\partial V}{\partial \lambda_j} \right) \wedge [\rho u] \right\}.$$

We also express $(\rho u)^+ \pm (\rho u)^-$ in terms of $[u]$ and V , and notice that

$$(3.9) \quad [u] \cdot \frac{\partial r}{\partial \lambda_j} = \frac{1}{\|N\|} \left(\frac{\partial r}{\partial \lambda_j}, N, \Omega \right).$$

We thus obtain

PROPOSITION 3.1. *If during a period of time, the interface between two ideal fluids of different densities superposed one over the other remains a smooth surface $\mathcal{S}(t) = \{\vec{r} = r(\vec{\lambda}, t) \text{ with } \vec{\lambda} = (\lambda_1, \lambda_2) \in R^2\}$ with a smooth (vectorial) vorticity density $\Omega(\vec{\lambda}, t)$, one has*

$$(3.10) \quad (a) \quad \left(V - \frac{\partial r}{\partial t} \right) \cdot N = 0, \\ (b) \quad \frac{\partial}{\partial t} \left(\frac{\Omega}{2} + \alpha(V \wedge N) \right) \\ + \sum_{j=1}^2 (-1)^{j+1} \frac{\partial}{\partial \lambda_j} \left\{ \frac{1}{\|N\|^2} \left(V - \frac{\partial r}{\partial t}, \frac{\partial r}{\partial \lambda_{\tilde{j}}}, N \right) \left(\frac{\Omega}{2} + \alpha V \wedge N \right) \right\} \\ + (-1)^{j+1} \left\{ \frac{1}{2\|N\|^2} \left(\frac{\partial r}{\partial \lambda_j}, N, \Omega \right) + \alpha \left(V \cdot \frac{\partial r}{\partial \lambda_j} \right) \right\} \frac{\partial V}{\partial \lambda_{\tilde{j}}} \\ + \alpha (-1)^{j+1} \frac{\partial}{\partial \lambda_j} \left(\frac{V^2}{2} - \frac{[u]^2}{8} \right) \frac{\partial r}{\partial \lambda_{\tilde{j}}} - \alpha \vec{g} \wedge N = 0,$$

where the jump of the velocity through the interface is given by

$$(3.11) \quad [u] = \frac{1}{\|N\|^2} \sum_{j=1}^2 (-1)^{j+1} \left(\Omega \cdot \frac{\partial r}{\partial \lambda_j} \right) \frac{\partial r}{\partial \lambda_{\tilde{j}}},$$

and V defined in (3.2).

This system simplifies when the interface can be resolved in the form $z = z(\vec{x}, t)$ with $\vec{x} = (x_1, x_2)$. (3.10) becomes

$$(3.12) \quad \begin{aligned} (a) \quad & \frac{\partial z}{\partial t} - V_3 + \frac{\partial z}{\partial x_1} V_1 + \frac{\partial z}{\partial x_2} V_2 = 0, \\ (b) \quad & \frac{\partial}{\partial t} \left(\frac{\Omega}{2} + \alpha V \wedge N \right) = S \end{aligned}$$

with

$$(3.13) \quad \begin{aligned} -S = & \sum_{j=1}^2 \frac{\partial}{\partial x_j} \left\{ V_j \left(\frac{\Omega}{2} + \alpha V \wedge N \right) \right\} - \left\{ \frac{\Omega_j}{2} + \alpha \left(V \cdot \frac{\partial r}{\partial x_j} \right) \right\} \frac{\partial V}{\partial x_j} \\ & + \alpha \frac{\partial}{\partial x_j} \left\{ \frac{|V|^2}{2} - \frac{|u|^2}{8} \right\} \frac{\partial r}{\partial x_j} + \alpha g \wedge N. \end{aligned}$$

Let us first consider the problem in R^3 . Developing $\partial(V \wedge N)/\partial t$, (3.12)(b) is rewritten in the form

$$(3.14) \quad \frac{\partial \Omega_i}{\partial t} + \alpha \sum_{j=1}^3 B_{ij} \{z\} \frac{\partial \Omega_j}{\partial t} = E_i \{\Omega, z\} \quad (i = 1, 2, 3).$$

The right-hand side of (3.14) is given by

$$(3.15) \quad E = S + I + J$$

with, for $i = 1, 2$,

$$(3.16) \quad \begin{aligned} I_j = & -\frac{\alpha}{4\pi} (-1)^{j+1} \frac{\partial}{\partial x_j} \int \frac{\partial z(\vec{x})/\partial t - \partial z(\vec{x}')/\partial t}{|r(\vec{x}) - r(\vec{x}')|^3} \\ & \times \{(x_2 - x'_2)\Omega_1(\vec{x}') - \Omega_2(\vec{x}')(x_1 - x'_1)\} d\vec{x}', \end{aligned}$$

$$(3.17) \quad \begin{aligned} I_3 = & -\frac{\alpha}{4\pi} \sum_{j=1}^2 \frac{\partial}{\partial x_j} \int \frac{\partial z(\vec{x})/\partial t - \partial z(\vec{x}')/\partial t}{|r(\vec{x}) - r(\vec{x}')|^3} \\ & \times \{(x_j - x'_j)\Omega_3(\vec{x}') - \Omega_j(\vec{x}')(z(\vec{x}) - z(\vec{x}'))\} d\vec{x}' \end{aligned}$$

and

$$(3.18) \quad \begin{aligned} J = & -\frac{\alpha}{4\pi} \int \frac{\partial z(\vec{x})/\partial t - \partial z(\vec{x}')/\partial t}{|r(\vec{x}) - r(\vec{x}')|^3} \\ & \times \left\{ 3 \frac{r(\vec{x}) - r(\vec{x}')}{|r(\vec{x}) - r(\vec{x}')|^2} [\Omega(\vec{x}') \cdot (r(\vec{x}) - r(\vec{x}'))] - \Omega(\vec{x}') \right\} d\vec{x}'. \end{aligned}$$

In the left-hand side of (3.14),

$$(3.19) \quad \begin{aligned} B\{z\} \frac{\partial \Omega}{\partial t} = & -\frac{1}{4\pi} \int \left\{ \left(N(\vec{x}) \cdot \frac{r(\vec{x}) - r(\vec{x}')}{|r(\vec{x}) - r(\vec{x}')|^3} \right) \frac{\partial \Omega}{\partial t}(\vec{x}') \right. \\ & \left. - \frac{r(\vec{x}) - r(\vec{x}')}{|r(\vec{x}) - r(\vec{x}')|^3} \left(N(\vec{x}) \cdot \frac{\partial \Omega}{\partial t}(\vec{x}') \right) \right\} d\vec{x}'. \end{aligned}$$

For a given z , B can be viewed as a linear integral operator acting on $\partial \Omega / \partial t$. Let B_{ij} be the matricial elements of this operator. The kernels of B_{3j} ($j = 1, 2, 3$)

will be “small” of the interface gradients are “small”. The kernels of B_{13} and B_{23} which operate on $\partial\Omega/\partial t$ have contributions which are independent of ∇z . In these terms, we make the replacement

$$(3.20) \quad \frac{\partial\Omega_3}{\partial t} = -\alpha \sum_{j=1}^3 B_{3j} \frac{\partial\Omega_j}{\partial t} + E_3\{\Omega, z\}.$$

The resulting operator acting on $\partial\Omega_j/\partial t$ is then “small” with ∇z .

PROPOSITION 3.2. *If, during a period of time, the interface between two ideal fluids of different densities superposed one over the other is a smooth surface $z = z(\vec{x}, t)$ with a smooth vorticity density $\Omega(\vec{x}, t)$, one has*

$$(3.21) \quad \begin{aligned} (a) \quad & \frac{\partial z}{\partial t} - V_3 + \frac{\partial z}{\partial x_1} V_1 + \frac{\partial z}{\partial x_2} V_2 = 0, \\ (b) \quad & \frac{\partial\Omega_j}{\partial t} + \alpha A_j\{z\} \frac{\partial\Omega}{\partial t} = F\{\Omega, z\} \quad (j = 1, 2, 3) \end{aligned}$$

with (no summation)

$$(3.22) \quad F_j\{\Omega, z\} = E_j\{\Omega, z\} + (1 - \delta_{3,j}) \int \frac{x_j - x'_j}{|r(\vec{x}) - r(\vec{x}')|^3} E_3\{\Omega, z\}(\vec{x}') d\vec{x}'$$

for $j = 1, 2$,

$$(3.23) \quad \begin{aligned} (a) \quad A_j\{z\} \frac{\partial\Omega}{\partial t} = & -\frac{1}{4\pi} \int \frac{1}{|r(\vec{x}) - r(\vec{x}')|^3} \\ & \times \left\{ -\frac{\partial z}{\partial x_j}(\vec{x}) \left((x_j - x'_j) \frac{\partial\Omega_j}{\partial t}(\vec{x}') - (x_j - x'_j) \frac{\partial\Omega_j}{\partial t}(\vec{x}') \right) \right. \\ & \left. + (z(\vec{x}) - z(\vec{x}')) \frac{\partial\Omega_j}{\partial t}(\vec{x}') + (x_j - x_j) B_3\{z\} \frac{\partial\Omega}{\partial t}(\vec{x}') \right\} d\vec{x}', \end{aligned}$$

$$(b) \quad A_3\{z\} \partial\Omega/\partial t = B_3\{z\} \partial\Omega/\partial t$$

and

$$(3.24) \quad V(\vec{x}) = -\frac{1}{4\pi} \int \frac{r(\vec{x}) - r(\vec{x}')}{|r(\vec{x}) - r(\vec{x}')|^3} \wedge \Omega(\vec{x}') d\vec{x}'.$$

For simplicity, the temporal argument has been omitted.

When a horizontal bottom is present at $z = 0$

$$(3.25) \quad V(\vec{x}) = -\frac{1}{4\pi} \int_{R^2} \left(\frac{r(x) - r(x')}{|r(\vec{x}) - r(\vec{x}')|^3} - \frac{r(x) - r(x')}{|r(\vec{x}) - \bar{r}(x')|^3} \right) \wedge \Omega(\vec{x}') d\vec{x}',$$

where $\bar{r}(\vec{x}) = (x_1, x_2, -z(x_1, x_2))$. When $\partial(V \wedge N)/\partial t$ is developed to write (3.12)(b) as a Fredholm equation, we get

$$(3.26) \quad \partial\Omega/\partial t + \alpha B\{z\} \partial\Omega/\partial t = E\{\Omega, z\},$$

where

$$(3.27) \quad \begin{aligned} B\{z\} \frac{\partial\Omega}{\partial t} = & -\frac{1}{4\pi} \int \left\{ N(\vec{x}) \cdot \left(\frac{r(\vec{x}) - r(\vec{x}')}{|r(\vec{x}) - r(\vec{x}')|^3} - \frac{r(\vec{x}) - \bar{r}(\vec{x}')}{|r(\vec{x}) - \bar{r}(\vec{x}')|^3} \right) \frac{\partial\Omega}{\partial t}(\vec{x}') \right. \\ & \left. - \left(N(\vec{x}) \cdot \frac{\partial\Omega}{\partial t}(\vec{x}') \right) \left(\frac{r(\vec{x}) - r(\vec{x}')}{|r(\vec{x}) - r(\vec{x}')|^3} - \frac{r(\vec{x}) - \bar{r}(\vec{x}')}{|r(\vec{x}) - \bar{r}(\vec{x}')|^3} \right) \right\} d\vec{x}' \end{aligned}$$

and

$$(3.28) \quad E = S + I + J$$

with

$$(3.29) \quad -S = \sum_{j=1}^2 \left\{ V_j \left(\frac{\Omega}{2} + \alpha V \wedge N \right) + \left(\frac{\Omega_j}{2} + \alpha \left(V \cdot \frac{\partial r}{\partial x_j} \right) \right) \right. \\ \left. \times \frac{\partial V}{\partial x_j} - \alpha \frac{\partial}{\partial x_j} \left(\frac{|V|^2}{2} - \frac{|u|^2}{8} \right) \right\} \frac{\partial r}{\partial x_j} + \alpha g \wedge N.$$

For $j = 1, 2$

$$(3.30) \quad I_j = \frac{-\alpha}{4\pi} (-1)^{j+1} \frac{\partial}{\partial x_j} \int \left(\frac{\partial z(\vec{x})/\partial t - \partial z(\vec{x}')/\partial t}{|r(\vec{x}) - r(\vec{x}')|^3} - \frac{\partial z(\vec{x})/\partial t + \partial z(\vec{x}')/\partial t}{|r(\vec{x}) - \bar{r}(\vec{x}')|^3} \right) \\ \times ((x_2 - x'_2)\Omega_1(\vec{x}') - \Omega_2(\vec{x}')(x_1 - x'_1)) d\vec{x}'$$

and

$$(3.31) \quad I_3 = -\frac{\alpha}{4\pi} \sum_{j=1}^2 \frac{\partial}{\partial x_j} \int \left\{ \left(\frac{\partial z(\vec{x})/\partial t - \partial z(\vec{x}')/\partial t}{|r(\vec{x}) - r(\vec{x}')|^3} - \frac{\partial z(\vec{x})/\partial t + \partial z(\vec{x}')/\partial t}{|r(\vec{x}) - \bar{r}(\vec{x}')|^3} \right) \right. \\ \times (x_j - x'_j)\Omega_3(\vec{x}')(x_j - x'_j)\Omega_3(\vec{x}') \\ \left. - \left(\frac{(\partial z(\vec{x})/\partial t - \partial z(\vec{x}')/\partial t)(z(\vec{x}) - z(\vec{x}'))}{|r(\vec{x}) - r(\vec{x}')|^3} \right. \right. \\ \left. \left. - \frac{(\partial z(\vec{x})/\partial t + \partial z(\vec{x}')/\partial t)(z(\vec{x}) + z(\vec{x}'))}{|r(\vec{x}) - \bar{r}(\vec{x}')|^3} \right) \Omega_j(\vec{x}') \right\} d\vec{x}',$$

$$(3.32) \quad J = -\frac{\alpha}{4\pi} \int \frac{\partial z(\vec{x})/\partial t - \partial z(\vec{x}')/\partial t}{|r(\vec{x}) - r(\vec{x}')|^3} \\ \times \left\{ 3 \frac{r(\vec{x}) - r(\vec{x}')}{|r(\vec{x}) - r(\vec{x}')|^2} (\Omega(\vec{x}') \cdot (r(\vec{x}) - r(\vec{x}')) - \Omega(\vec{x}')) \right\} \\ - \frac{\partial z(\vec{x})/\partial t + \partial z(\vec{x}')/\partial t}{|r(\vec{x}) - \bar{r}(\vec{x}')|^3} \left\{ 3 \frac{r(\vec{x}) - \bar{r}(\vec{x}')}{|r(\vec{x}) - \bar{r}(\vec{x}')|^2} (\Omega(\vec{x}') \cdot (r(\vec{x}) - \bar{r}(\vec{x}')) - \Omega(\vec{x}')) \right\}.$$

Assume that $z(\vec{x}, t)$ fluctuates around some mean value h . As in two dimensions, we isolate the linear contribution by writing

$$(3.33) \quad z(\vec{x}, t) = h + \eta(\vec{x}, t).$$

For the two first components of $B\{z\}\partial\Omega/\partial t$, we write

$$(3.34) \quad \frac{z(\vec{x}) + z(\vec{x}')}{|r(\vec{x}) - \bar{r}(\vec{x}')|^3} = \frac{2h}{\{(\vec{x} - \vec{x}')^2 + 4h^2\}^{3/2}} + \left\{ \frac{z(\vec{x}) + z(\vec{x}')}{|r(\vec{x}) - r(\vec{x}')|^3} - \frac{2h}{\{(\vec{x} - \vec{x}')^2 + 4h^2\}^{3/2}} \right\}$$

and, like in the case of the whole space, we make the replacement

$$(3.35) \quad \partial\Omega_3/\partial t = E_3\{\Omega, z\} - B_3\{z\}\partial\Omega/\partial t$$

in the term which does not contain the interface gradient. We obtain

$$(3.36) \quad \frac{\partial \Omega_j}{\partial t} + \alpha \int \frac{2h}{\{(\vec{x} - \vec{x}')^2 + 4h^2\}^{3/2}} \frac{\partial \Omega_j}{\partial t}(\vec{x}') d\vec{x}' = -\alpha A_j\{z\} \frac{\partial \Omega}{\partial t} + F_j\{\Omega, z\}$$

for $j = 1, 2$ and

$$(3.37) \quad \partial \Omega_3 / \partial t + A_3\{z\} \partial \Omega / \partial t = F_3\{\Omega, z\}.$$

For $j = 1, 2$

$$(3.38) \quad F_j\{\Omega, z\} = E_j\{\Omega, z\} + \int \left(\frac{x_j - x'_j}{|r(\vec{x}) - r(\vec{x}')|^3} - \frac{x_j - x'_j}{|r(\vec{x}) - \bar{r}(\vec{x}')|^3} \right) E_3\{\Omega, z\}(\vec{x}') d\vec{x}',$$

$$(3.39) \quad A_j\{z\} \frac{\partial \Omega}{\partial t} = -\frac{1}{4\pi} \int \left(\frac{1}{|r(\vec{x}) - r(\vec{x}')|^3} - \frac{1}{|r(\vec{x}) - \bar{r}(\vec{x}')|^3} \right) \\ \times \left\{ \frac{\partial z}{\partial x_j}(\vec{x}) \left((x_j - x'_j) \frac{\partial \Omega_j}{\partial t}(\vec{x}') - (x_j - x'_j) \frac{\partial \Omega_j}{\partial t}(\vec{x}') \right) \right. \\ \left. + (x_j - x'_j) B_3\{z\} \frac{\partial \Omega}{\partial t}(\vec{x}') \right\} + \frac{z(\vec{x}) - z(\vec{x}')}{|r(\vec{x}) - r(\vec{x}')|^3} \frac{\partial \Omega_j}{\partial t}(\vec{x}') \\ + \left\{ \frac{z(\vec{x}) + z(\vec{x}')}{|r(\vec{x}) - \bar{r}(\vec{x}')|^3} - \frac{2h}{\{(\vec{x} - \vec{x}')^2 + 4h^2\}^{3/2}} \right\} \frac{\partial \Omega_j}{\partial t}(\vec{x}') d\vec{x}'$$

and

$$(3.40) \quad A_3\{z\} \partial \Omega / \partial t = B_3\{z\} \partial \Omega / \partial t,$$

$$(3.41) \quad F_3\{\Omega, z\} = E_3\{\Omega, z\}.$$

The linear operator acting on $\partial \Omega / \partial t$ in the left-hand side of (3.36) is inverted by taking the Fourier transform of the equation (see Appendix). We finally obtain

PROPOSITION 3.3. *When the Rayleigh-Taylor problem is considered in the half-space $z > 0$ and the interface can be resolved in the form $z = z(\vec{x}, t) \equiv h + \eta(\vec{x}, t)$, the equations of motion read*

$$(3.42) \quad \begin{aligned} (a) \quad & \frac{\partial z}{\partial t} - V_3 + \frac{\partial z}{\partial x_1} V_1 + \frac{\partial z}{\partial x_2} V_2 = 0, \\ (b) \quad & \frac{\partial \Omega_j}{\partial t} + \alpha \mathcal{G}(\vec{x}) * \left(A_j\{z\} \frac{\partial \Omega_j}{\partial t} \right) = \mathcal{G}(\vec{x}) * F_j\{\Omega, z\}, \quad j = 1, 2, \\ (c) \quad & \frac{\partial \Omega_3}{\partial t} + A_3\{z\} \frac{\partial \Omega}{\partial t} = F_3\{\Omega, z\}, \end{aligned}$$

where

$$(3.43) \quad \mathcal{G}(\vec{x}) = \int_0^\infty \frac{2hk J_0(k|x|)}{1 + \alpha e^{-2hk}} dk$$

belongs to $L^1(R^2)$ (see Appendix) and where the operators A and F are defined in (3.38)–(3.41).

4. A Cauchy-Kowalewski theorem for a nonlinear problem of Fredholm type. Let $\mathcal{B} = \{B_s\}$ for $0 < s \leq s_0$ be a scale of decreasing Banach spaces, i.e. for any $0 < s' < s \leq s_0$

$$B_s \subset B_{s'}, \quad \| \cdot \|_{s'} \leq \| \cdot \|_s.$$

Consider in $\mathcal{B}^2 = \{B_s^2\}$ the initial value problem for $X = (X_1, X_2)$ of the form ($\alpha \in R$)

$$(4.1) \quad \begin{aligned} \partial X_1 / \partial t + \alpha A(t, X_2) \partial X_1 / \partial t &= F_1(t, X), \quad \partial X_2 / \partial t = F_2(t, X), \\ X_1(0) &= X_1^{(0)}, \quad X_2(0) = X_2^{(0)}. \end{aligned}$$

We assume that $X_1^{(0)}$ and $X_2^{(0)}$ are in B_{s_0} with $\|X_1^{(0)}\|_s < R_1^{(0)}$ and $\|X_2^{(0)}\|_s < R_2^{(0)}$. We define

$$\mathcal{E}_s(R_1, R_2) = \{X \in B_s^2, \|X_1\|_s < R_1, \|X_2\|_s < R_2\}$$

and assume the following hypothesis on $F = (F_1, F_2)$ and A . For some positive numbers $R_0 > 2R_0^{(1)}$, $R_2 > 2R_0^{(2)}$ and T , let $(t, X) \rightarrow F(t, X)$ be a continuous mapping of $[-T, T] \times \mathcal{E}_s(R_1, R_2)$ into B_s^2 , satisfying for any $0 < s' < s \leq s_0$ and all $X, \tilde{X} \in \mathcal{E}_s(R_1, R_2)$

$$(H1) \quad \|F(t, X) - F(t, \tilde{X})\|_{s'} \leq \frac{C_F}{s - s'} \|X - \tilde{X}\|_s,$$

where C_F is a constant independent of $t, X, \tilde{X}, s, s'$, but possibly dependent on R_1 and R_2 . In addition, for $0 < s < s_0$

$$(H2) \quad \sup_{|t| < T} \|F(t, X^{(0)})\|_s \leq \frac{M}{s_0 - s}.$$

In (H1) and (H2), the norm in B_s^2 is defined as

$$\|Y\|_s = \|Y_1\|_s + \|Y_2\|_s \quad \text{for } Y = (Y_1, Y_2) \in B_s^2.$$

Let $A(t, X_2)Y_1$ be a continuous mapping of $\{X_2, Y_1 \in B_s, \text{ with } \|X_2\| < R_2\}$ into B_s , linear in Y_1 and satisfying, for any $0 < s \leq s_0$ and all $X_2, Y_1, \tilde{X}_2, \tilde{Y}_1 \in B_s$, with $\|X_2\|_s < R_2$ and $\|\tilde{X}_2\|_s < R_2$,

$$(H3) \quad \sup_{|t| < T} \|A(t, X_2)Y_1 - A(t, X_2)\tilde{Y}_1\|_s \leq C_A \|Y_1 - \tilde{Y}_1\|_s,$$

$$(H4) \quad \sup_{|t| < t} \|A(t, X_2)Y_1 - A(t, \tilde{X}_2)Y_1\|_s \leq C'_A \|Y_1\|_s \|X_2 - \tilde{X}_2\|_s,$$

where C_A and C'_A are constants independent of $t, X_2, \tilde{X}_2, Y_1, \tilde{Y}_2, s$ but possibly dependent on R_2 .

THEOREM 4.1. *If there exists a constant $c_* < 1$ such that (H1) and (H4) are satisfied with $|\alpha|C_A < c_*$, then there is a positive constant a and a unique function $X(t)$ which, for every $s \in (0, s_0)$, is continuously differentiable in $(-a(s_0 - s), a(s_0 - s))$, valued in B_s^2 with*

$$\sup_{|t| < a(s_0 - s)} \|X_1(t)\|_s < R_1 \quad \text{and} \quad \sup_{|t| < a(s_0 - s)} \|X_2(t)\|_s < R_2$$

and satisfies (4.1).

REMARK 4.1. If (H3) can be replaced by

$$(H'3) \quad \|A(t, X_2)Y_1 - A(t, X_2)\tilde{Y}_1\|_s \leq \tilde{C}_A \|X_2\|_s \|Y_1 - \tilde{Y}_1\|_s,$$

the smallness condition on the constant C_A is replaced by a constraint on the initial data, namely $|\alpha|\tilde{C}_A\|X_2^{(0)}\|_s < 1$, so that the coefficient of $\partial X_1/\partial t$ is not 0.

REMARK 4.2 If, in addition to (H1)–(H4) with t complex, F and A satisfy the assumption:

If $0 < s' < s < s_0$, and X holomorphic for $t \in C$, $|t| < T$ valued in B_s , then $t \rightarrow F(t, X(t))$ and $t \rightarrow A(t, X_2(t))Y_1(t)$ are holomorphic functions for $|t| < T$ valued in B'_s and B_s , respectively, then X is a holomorphic function of t with values in $(B_s)^2$.

Proof of Theorem 4.1. Baouendi and Goulaouic's proof [14] of the Cauchy-Kowalewski Theorem as formulated by Nishida [13] for (4.1) with $A = 0$ is easily extended to equations of Fredholm type.

For every $a > 0$, E_a denotes the Banach space of functions $u(t)$ which for every $s \in (0, s_0)$ are continuous for $|t| < a(s_0 - s)$, valued in B_s and satisfy

$$(4.2) \quad |||u|||_a = \sup_{|t| < a(s_0 - s)} \|u(t)\|_s (s_0 - s) \left(1 - \frac{|t|}{a(s_0 - s)}\right)^{1/2} < \infty.$$

The space E_a is equipped with the norm $||| \cdot |||_a$.

Denoting

$$(4.3) \quad Y = (Y_1, Y_2) = dX/dt,$$

one has

$$(4.4) \quad X = \mathcal{H}Y \equiv (X_1^{(0)} + \int_0^t Y_1(\tau) d\tau, X_2^{(0)} + \int_0^t Y_2(\tau) d\tau)$$

and (4.1) is rewritten as

$$(4.5) \quad Y_1 + \alpha A(t, \mathcal{H}Y)Y_1 = F_1(t, \mathcal{H}Y), \quad Y_2 = F_2(t, \mathcal{H}Y).$$

Straightforward adaptation of Lemmas 1–3 of [14] to the case of nonzero initial data leads to

LEMMA 4.1. *Let $a > 0$, $s \in (0, s_0)$ and $|t| < a(s_0 - s)$. If $X \in (E_a)^2$, one has the following properties:*

$$(4.6) \quad (i) \quad \|\mathcal{H}Y\|_s \leq \|X^{(0)}\|_s + 2a|||Y|||_a.$$

$$(4.7) \quad (ii) \quad \int_0^t \frac{\|Y(\tau)\|_s}{s(\tau) - s} d\tau \leq 8a \frac{|||Y|||_a}{s_0 - s} \sqrt{\frac{a(s_0 - s)}{a(s_0 - s) - |t|}}$$

with $s(\tau) = \frac{1}{2}(1 + s - |\tau|/a)$.

(iii) *If $Y \in (E_a)^2$ with $|||Y_1|||_a < R_1/8a$, $|||Y_2|||_a < R_2/8a$ and $\tilde{Y} \in (E)_{2a}^2$ with $|||\tilde{Y}_1|||_{2a} < R_1/16a$ and $|||\tilde{Y}_2|||_{2a} < R_2/16a$, then, under hypothesis (H1),*

$$(4.8) \quad \|F(t, \mathcal{H}Y(t)) - F(t, \mathcal{H}\tilde{Y}(t))\|_s \leq C \int_0^t \frac{\|Y(\tau) - \tilde{Y}(\tau)\|_{s(\tau)}}{s - s(\tau)} d\tau,$$

where $s(\tau)$ is any continuous function on $(0, t)$ satisfying $s < s(\tau) \leq \frac{1}{2}(s + s_0 - |\tau|/a)$. $\mathcal{H}Y(t)$ is defined in (4.4) and

$$(4.9) \quad \tilde{X}(t) = \mathcal{H}\tilde{Y}(t) \equiv \left(X_1^{(0)} + \int_0^t \tilde{Y}_1(\tau) d\tau, X_2^{(0)} + \int_0^t \tilde{Y}_2(\tau) d\tau\right).$$

(4.1) is rewritten in the form

$$(4.10) \quad Y = G(Y)$$

with

$$(4.11) \quad G_1(Y) = F_1(t, \mathcal{Y}Y) = \alpha A(t, \mathcal{Y}F_2(t, \mathcal{Y}Y))Y_1, \quad G_2(Y) = F_2(t, \mathcal{Y}Y).$$

Let $b \in (0, T)$. If for $|t| < b(s_0 - s)$ and $s \in (0, s_0)$, $Y \in E_b$ and $|||Y|||_b < R/2b$, one has

$$(4.12) \quad \begin{aligned} \|G(Y(t))\|_s &\leq \|F(t, \mathcal{Y}Y(t))\|_s + |\alpha| \|A(t, \mathcal{Y}F_2(t, \mathcal{Y}Y))Y_1\|_s \\ &\leq \|F(t, \mathcal{Y}Y(t)) - F(t, X^{(0)})\|_s + \|F(t, X^{(0)})\|_s \\ &\quad + |\alpha| \|A(t, \mathcal{Y}F_2(t, \mathcal{Y}Y))Y_1\|_s. \end{aligned}$$

Lemma 4.1 and hypotheses (H1)–(H3) imply

$$(4.13) \quad \|G(Y(t))\|_s \leq \frac{8bc}{s_0 - s} |||Y|||_b \sqrt{\frac{b(s_0 - s)}{b(x_0 - s) - |t|}} + \frac{M}{s_0 - s} + |\alpha| C_A \|Y_1\|_s,$$

$$(4.14) \quad |||G(Y)|||_b \leq 8bc |||Y|||_b + M + |\alpha| C_A |||Y_1|||_b.$$

This inequality insures that, for $a \in (0, T/2)$, $Y \in (E_a)^2$ with $|||Y_i||| < R_i/8a$ and $\tilde{Y} \in (E_{2a})^2$ with $|||\tilde{Y}_i|||_{2a} < R_i/16a$ ($i = 1, 2$), $G(Y)$ and $G(\tilde{Y})$ are in $(E_a)^2$. Furthermore,

$$(4.15) \quad \begin{aligned} \|G(Y(t)) - G(\tilde{Y}(t))\|_s &\leq \frac{8aC}{s_0 - s} |||Y - \tilde{Y}|||_a \sqrt{\frac{a(s_0 - s)}{a(s_0 - s) - |t|}} \\ &\quad + |\alpha| C_A \|Y_1(t) - \tilde{Y}_1(t)\|_s \\ &\quad + |\alpha| C'_A \|Y_1(t)\|_s \|\mathcal{Y}F_2(t, \mathcal{Y}Y) - \mathcal{Y}F_2(t, \mathcal{Y}\tilde{Y})\|_s \end{aligned}$$

with

$$(4.16) \quad \begin{aligned} \|\mathcal{Y}F_2(t, \mathcal{Y}Y) - \mathcal{Y}F_2(t, \mathcal{Y}\tilde{Y})\|_s &\leq \int_0^t \|F_2(\tau, \mathcal{Y}Y(\tau)) - F_2(\tau, \mathcal{Y}\tilde{Y}(\tau))\|_s d\tau \\ &\leq \int_0^t C \left(\int_0^\tau \frac{\|Y(\tau') - \tilde{Y}(\tau')\|_{s(\tau')}}{s - s(\tau')} d\tau' \right) d\tau \\ &\leq C 8a \frac{|||Y - \tilde{Y}|||_a}{s_0 - s} \int_0^t \sqrt{\frac{a(s_0 - s)}{a(s_0 - s) - |\tau|}} d\tau \\ &\leq 16Ca^2 |||Y - \tilde{Y}|||_a. \end{aligned}$$

Substituting in (4.15) we obtain

$$(4.17) \quad |||G(Y) - G(\tilde{Y})||| \leq K |||Y - \tilde{Y}|||_a$$

with

$$(4.18) \quad K = a(8C + 2|\alpha|C'_A C R_1) + |\alpha|C_A.$$

The constant K will be smaller than 1 if $|\alpha|C_A < C < 1$ and

$$a < a_* = (1 - C_*)/(8C + 2|\alpha|C'_A C R_1).$$

Let E denote the closure of E_a of the ball

$$\beta_{2a} = \{Y \in E_{2a}, |||Y_i|||_{2a} < R_i/16a, i = 1, 2\}.$$

E is a complete metric space contained in $\{Y \in E_a, |||Y_i|||_a < R_i/16a (i = 1, 2)\}$. Under the conditions $|\alpha|C_A < C_* < 1$ and $a < \inf(T/2, a_*, a_{**})$ with

$$a_{**} = \inf\left(\frac{(1 - C_*)R_1}{16(C \sup_i R_i + M)}, \frac{R_2}{16(C \sup_i R_i + M)}\right),$$

G is a contracting mapping of E into itself. Hence G has a unique fixed point Y in E which is a solution of (4.1).

If (H3) is replaced by (H'3), the constant C_A is replaced by

$$C_A(||X_2^{(0)}||_s + 16Ca^2|||Y|||_a + aM)$$

in (4.14) and (4.15). The constant K in (3.16) becomes

$$K = a \left\{ 8c + 2|\alpha|C \left(C'_A R_1 + \tilde{C}_A \sup_{i=1,2} R_i \right) + |\alpha|M \right\} + |\alpha|C_A ||X_2^{(0)}||_s.$$

The conditions which insure that G is a contracting mapping of E into itself are now $|\alpha|C_A ||X_2^{(0)}||_s < C_* < 1$ and $a < \inf(T/2, a_*, a_{**})$ with

$$a_* = \frac{(1 - C_*)}{8C + 2|\alpha|C(C_A R_1 + \tilde{C}_a \sup R_i) + |\alpha|M},$$

$$a_{**} = \inf\left(\frac{(1 - C_*)R_1}{16(C \sup_i R_i + M)(1 + \alpha \tilde{C}_A R_1)}, \frac{R_2}{16(C \sup_i R_i + M)}\right).$$

5. Finite time analyticity for the Rayleigh-Taylor problem in the entire space. We look for solutions of systems (2.16), (2.17) and (3.21) such that $\{\Omega, y, y_x\}$ in two dimensions and $\{\tilde{\Omega}, z, \nabla z\}$ in three dimensions are analytic functions defined in

$$(5.1) \quad b_s = \{(\vec{x}, \vec{\sigma}), x \in R^d, |\vec{\sigma}| < s\}, \quad d = 1 \text{ or } 2,$$

with the additional condition that Ω and y_x or ∇z belong to $L^2(R^d + i\vec{\sigma})$ ($|\vec{\sigma}| < s, d = 1, 2$). We defined the norms

$$(5.2) \quad |u|_s = \sup_{x+i\sigma \in b_s} |u(x+i\sigma)|,$$

$$\|u\|_s = |u|_s + \sup_{\substack{x+i\sigma \in b_s \\ x+i\sigma \in b_s}} \frac{|u(x+i\sigma) - u(x'+i\sigma)|}{|x-x'|^\alpha}, \quad 0 < \alpha < 1,$$

$$\|u\|_{L_s^2}^2 = \sup_{|\sigma| < s} \int_{R^d} |u(x+i\sigma)|^2 dx, \quad |||u|||_s = \|u\|_s + \|u\|_{L_s^2}.$$

$B_s^{(1)}$ and $B_s^{(2)}$ are, respectively, the spaces of analytic functions u defined in b_s such that $\|u\|_s$ and $|||u|||_s$ are bounded.

a. *Two dimensional flows.* For $|\text{Im } y_x|_s < 1$ (so that the denominator is not cancelled in (5.3)), V and A are continued analytically to the strip b_s in the form (5.3)

$$V_1\{\Omega, y\}(x+i\sigma) = -\frac{1}{2\pi} \int \frac{y(x+i\sigma) - y(x'+i\sigma)}{(x-x')^2 + (y(x+i\sigma) - y(x'+i\sigma))^2} \Omega(x'+i\sigma) dx',$$

$$(5.4) \quad V_2\{\Omega, y\}(x+i\sigma) = \frac{1}{2\pi} \int \frac{x-x'}{(x-x')^2 + (y(x+i\sigma) - y(x'+i\sigma))^2} \Omega(x'+i\sigma) dx',$$

$$(5.5) \quad \left(A\{y\} \frac{\partial \Omega}{\partial t} \right) (x+i\sigma) \\ = \frac{-1}{2\pi} \int \frac{y(x+i\sigma) - y(x'+i\sigma) - y_x(x+i\sigma)(x-x')}{(x-x')^2 + (y(x+i\sigma) - y(x'+i\sigma))^2} \Omega(x'+i\sigma) dx'.$$

V_1, V_2 and A satisfy

PROPOSITION 5.1. *If $y \in B_s^{(1)}$ and $y_x, \Omega, \xi \in B_s^{(2)}$ with $|\operatorname{Im} y_x|_s < \kappa < 1$, $|||y_x|||_s < R_2$, and similar conditions for $\tilde{y}, \tilde{y}_x, \tilde{\Omega}, \tilde{\xi}$, then the analytic continuation of V and A to complex values of the space variable satisfies*

$$(5.6) \quad |||V_1\{\Omega, y\} - V_1\{\tilde{\Omega}, \tilde{y}\}|||_s \leq C(1 + R_2^2)(|||y_x|||_s |||\Omega - \tilde{\Omega}|||_s + |||\tilde{\Omega}|||_s |||y_x - \tilde{y}_x|||_s),$$

$$(5.7) \quad |||V_2\{\Omega, y\} - V_2\{\tilde{\Omega}, \tilde{y}\}|||_s \leq C(1 + R_2^2)(|||\Omega - \tilde{\Omega}|||_s + |||\tilde{\Omega}|||_s |||y_x - \tilde{y}_x|||_s),$$

$$(5.8) \quad |||A\{y\}\xi - A\{\tilde{y}\}\tilde{\xi}|||_s \leq C|||y_x|||_s(1 + R_2^2)|||\xi - \tilde{\xi}|||_s,$$

$$(5.9) \quad |||A\{y\}\xi - A\{\tilde{y}\}\xi|||_s \leq C(1 + R_2^2)|||\xi|||_s |||y_x - \tilde{y}_x|||_s,$$

where C is a numerical constant.

PROOF. Inequalities (5.6) and (5.7) are established in [12] with an additional term $|y - \tilde{y}|_s$ in the right-hand side. One can actually avoid the introduction of this term by modifying in the estimate of $|V_1\{\Omega, y\} - V_1\{\tilde{\Omega}, \tilde{y}\}|_{L_s^2}$ the contribution of the term

$$(5.10) \quad b = \int dx \left(\int dx' \theta_2(|x-x'|) \frac{(\Omega(x'+i\sigma) - \tilde{\Omega}(x'+i\sigma))(y(x+i\sigma) - y(x'+i\sigma))}{(x-x')^2 + (y(x+i\sigma) - y(x'+i\sigma))^2} \right)^2,$$

where $\theta_2(|x|) = 1 - \theta_1(|x|)$ and θ_1 is a smooth function with compact support equal to 1 in a neighborhood of $x = 0$. We write

$$(5.11) \quad |b| \leq |\Omega - \tilde{\Omega}|_{L_s^2}^2 \int dx \left(\int dx' \frac{\theta_2^2(|x-x'|)}{|x-x'|^2} \int_0^1 |y_x(\lambda x + (1-\lambda)x')|^2 d\lambda \right) \\ \leq |\Omega - \tilde{\Omega}|_{L_s^2}^2 \int dx \frac{\theta_2^2(|x|)}{|x|^2} \int dx' \int_0^1 d\lambda |y_x(\lambda x + x')|^2 d\lambda \\ \leq C|\Omega - \tilde{\Omega}|_{L_s^2}^2 |y_x|_{L_s^2}^2.$$

The inequalities (5.8) and (5.9) are easily obtained by noticing that

$$(5.12) \quad A\{y\}\xi = V_1\{y, \xi\} + y_x V_2\{y, \xi\}$$

and using (5.6) and (5.7).

Using that an analytic function in b_s satisfies

$$(5.13) \quad |||\nabla f|||_{s'} \leq \frac{1}{s-s'} |||f|||_s$$

for $s' < s$, one easily checks that the system of equations

$$(5.14) \quad \frac{\partial \Omega}{\partial t} + \alpha A\{y\} \frac{\partial \Omega}{\partial t} = F, \quad \frac{\partial y}{\partial t} - V_2 + y_x V_1 = 0,$$

$$\frac{\partial}{\partial t} y_x - \frac{\partial V_2}{\partial x} + \frac{\partial}{\partial x} (y_x V_1) = 0,$$

with initial conditions

$$(5.15) \quad \Omega(x, 0) = \Omega_0(x) \in B_s^{(2)}, \quad y(x, 0) = y_0(x) \in B_s^{(1)}, \quad y_x(x, 0) = y_{x,0}(x) \in B_s^{(2)},$$

satisfies the hypothesis of Theorem 4.1. Since only $|||y_x|||_s$ (and not $|||y|||_s$) appears in the right-hand side of (5.8), the condition for existence of a solution will be $|\alpha| |||y_{x,0}|||_s$ sufficiently small. We thus obtain

THEOREM 5.1. *There exists a constant k_0 , such that for initial conditions $(y_0, dy_0/dx, \Omega_0)$ whose analytic continuation belongs to $B_s^{(1)} \times B_s^{(2)} \times B_s^{(2)}$ with the conditions $|\text{Im}(dy_0/dx)|_{s_0} < \kappa < 1$ and $|\alpha| |||dy_0/dx|||_{s_0} < k_0$, there exists a constant a , such that for $|t| < a(s_0 - s)$, the system (5.14) has a unique solution $(y, dy/dx, \Omega)$ which is an analytic function of t with value in $B_s^{(1)} \times B_s^{(2)} \times B_s^{(2)}$.*

b. *Three-dimensional flows.* For $|\nabla z|_s < \kappa < 1$, the operators entering in (3.21) are analytically continued to the strip b_s according to the following procedure: if

$$(5.16) \quad P(\vec{x}) = \int_{R^2} \mathcal{P}(\vec{x}, \vec{x}') d\vec{x}'$$

then

$$(5.17) \quad P(\vec{x} + i\vec{\sigma}) = \int_{R^2} \mathcal{P}(\vec{x} + i\vec{\sigma}, \vec{x}' + i\vec{\sigma}') d\vec{x}'.$$

One has

PROPOSITION 5.2. *If $z \in B_s^{(1)}$ and $\nabla z, \Omega, \xi \in B_s^{(2)}$ with $|\text{Im} \nabla z|_s < K < 1$, $|||\nabla z|||_s < R_2$ and similar conditions for $\tilde{z}, \nabla \tilde{z}, \tilde{\Omega}, \tilde{\xi}$, then the analytic continuation to b_s of the operators defined in (3.24), (3.13), (3.16)–(3.18) and (3.23) satisfies ($0 < s' < s$)*

$$(5.18) \quad |||V\{\Omega, z\} - V\{\tilde{\Omega}, \tilde{z}\}|||_s \leq C(R_2)(|||\Omega - \tilde{\Omega}|||_s + |||\tilde{\Omega}|||_s |||\nabla z - \nabla \tilde{z}|||_s),$$

$$(5.19) \quad |||S\{\Omega, z\} - S\{\tilde{\Omega}, \tilde{z}\}|||_{s'} \leq \frac{C(R_2)}{s - s'} (|||\Omega - \tilde{\Omega}|||_s + |||\tilde{\Omega}|||_s |||\nabla z - \tilde{z}|||_s),$$

$$(5.20) \quad |||I\{\Omega, z\} - I\{\tilde{\Omega}, \tilde{z}\}|||_{s'} \leq \frac{C(R_2)}{s - s'} (|||\Omega - \tilde{\Omega}|||_2 + |||\tilde{\Omega}|||_s |||\nabla z - \nabla \tilde{z}|||_s),$$

$$(5.21) \quad |||J\{\Omega, z\} - J\{\tilde{\Omega}, \tilde{z}\}|||_{s'} \leq \frac{C(R_2)}{s - s'} (|||\Omega - \tilde{\Omega}|||_s + |||\tilde{\Omega}|||_s |||\nabla z - \nabla \tilde{z}|||_s),$$

$$(5.22) \quad |||A_j\{z\}\xi - A_j\{\tilde{z}\}\tilde{\xi}||| \leq C(R_2) |||\nabla z|||_s |||\xi - \tilde{\xi}|||_s,$$

$$(5.23) \quad |||A_j\{z\}\xi - A_j\{\tilde{z}\}\tilde{\xi}||| \leq C(R_2) |||\xi|||_s |||\nabla z - \nabla \tilde{z}|||_s.$$

PROOF. One uses the following inequalities proved in [10]:

$$\begin{aligned}
 (5.24) \quad & \left\| \int \frac{x_i - x'_i}{|r(\vec{x} + i\vec{\sigma}) - r(\vec{x}' + i\vec{\sigma})|^3} \xi(\vec{x}' + i\vec{\sigma}) dx' \right. \\
 & \quad \left. - \int \frac{x_i - x'_i}{|\tilde{r}(\vec{x} + i\vec{\sigma}) - \tilde{r}(\vec{x}' + i\vec{\sigma})|^3} \tilde{\xi}(\vec{x}' + i\vec{\sigma}) d\vec{x}' \right\|_s \\
 & \leq (1 + C(R_2)) \{ \|\xi - \tilde{\xi}\|_s + R_2 \|\tilde{\xi}\|_s \|\nabla z - \nabla \tilde{z}\|_s \}, \quad i = 1, 2,
 \end{aligned}$$

and

$$\begin{aligned}
 (5.25) \quad & \left\| \int \frac{z(\vec{x} + i\vec{\sigma}) - z(\vec{x}' + i\vec{\sigma})}{|r(\vec{x} + i\vec{\sigma}) - r(\vec{x}' + i\vec{\sigma})|^3} \xi(x' + i\sigma) dx' \right. \\
 & \quad \left. - \int \frac{\tilde{z}(\vec{x} + i\vec{\sigma}) - \tilde{z}(\vec{x}' + i\vec{\sigma})}{|\tilde{r}(\vec{x} + i\vec{\sigma}) - \tilde{r}(\vec{x}' + i\vec{\sigma})|^3} \tilde{\xi}(x + i\sigma) d\vec{x}' \right\|_s \\
 & \leq (1 + C(R_2)) \|\nabla z\|_s (\|\xi - \tilde{\xi}\|_s + \|\xi\|_x \|\nabla z - \nabla \tilde{z}\|_s),
 \end{aligned}$$

where

$$(\vec{x} + i\vec{\sigma}) = (x_1 + i\sigma_1, x_2 + i\sigma_2, z(\vec{x} + i\vec{\sigma}))$$

and

$$r(\vec{x} + i\vec{\sigma}) = (x_1 + \sigma_1, x_2 + i\sigma_2, \tilde{z}(\vec{x} + i\vec{\sigma})).$$

$C(R_2)$ denotes a constant depending on R_2 .

To prove (5.21), we also use (3.21)(a),

$$(5.26) \quad \frac{\partial z}{\partial t}(\vec{x} + i\vec{\sigma}) - \frac{\partial z}{\partial t}(\vec{x}' + i\vec{\sigma}) = (\vec{x} - \vec{x}') \cdot \nabla \int_0^1 \left(V_3 - \frac{\partial z}{\partial x_1} V_1 - \frac{\partial z}{\partial x_2} \right) (\lambda \vec{x} + (1 - \lambda) \vec{x}') d\lambda$$

and (5.13). This leads to

THEOREM 5.2. *There exists a constant k_0 such that, for initial conditions $(z_0, \nabla z_0, \Omega_0)$ whose analytic continuation belongs to $B_s^{(1)} \times B_{s_0}^{(2)} \times B_{s_0}^{(2)}$ with the conditions $|\operatorname{Im} \nabla z_0|_{s_0} < K < 1$ and $|\alpha| \|\nabla z_0\|_{s_0} < k_0$, there exists a constant a such that for $|t| < a(s_0 - s)$, the system (3.21) has a unique solution $(z, \nabla z, \Omega)$ which is an analytic function of t with values in $B_s^{(1)} \times B_s^{(1)} \times B_s^{(2)}$.*

6. Local analyticity for the Rayleigh-Taylor problem in half a space.

We shall show in this section that the systems (2.28) and (3.42), for the Rayleigh-Taylor problem in half a space, in two and three dimensions, respectively, satisfy the hypothesis to the Cauchy-Kowalewski Theorem given in §4.

$$(6.2) \quad A\{y\}\xi(x+i\sigma) = C_h\{\eta\}\xi(x+i\sigma) + \int \mathcal{G}(x-x')C_h\{\eta\}\xi(x'+i\sigma) dx'$$

with

$$(6.3) \quad \begin{aligned} C_h\{\eta\}\xi(x+i\sigma) &= \frac{\alpha}{2\pi} \int \left\{ \frac{\eta(x+i\sigma) + \eta(x'+i\sigma) - \eta_2(x+i\sigma)(x-x')}{(x-x')^2 + (y(x+i\sigma) + y(x'+i\sigma))^2} \right. \\ &\quad + 2h \frac{(\eta(x+i\sigma) + \eta(x'+i\sigma))(y(x+i\sigma) + y(x'+i\sigma) + 2h)}{[(x-x')^2 + (y(x+i\sigma) + y(x'+i\sigma))^2][(x-x')^2 + 4h^2]} \\ &\quad \left. - \frac{\eta(x+i\sigma) - \eta(x'+i\sigma) - \eta_x(x+i\sigma)(x-x')}{(x-x')^2 + (\eta(x+i\sigma) - \eta(x'+i\sigma))^2} \right\} \\ &\quad \times \xi(x'+i\sigma) dx'. \end{aligned}$$

$\mathcal{G}(x)$ given in (2.31) and $y(x+i\sigma) = h + \eta(x+i\sigma)$.

The denominators do not vanish if $|\operatorname{Im} y_x|_s < K < 1$ and $|\eta|_s < \gamma h$, where γ is a positive number smaller than one. We shall see that the introduction of the L^2 -norm of the functions y_x and Ω can be avoided because the kernels of V_1 and V_2 decrease at least like $|x-x'|^{-2}$ at infinity.

PROPOSITION 6.1. *For $\eta, \eta_x, \Omega, \xi$ and $\tilde{\eta}, \tilde{\eta}_x, \tilde{\Omega}, \tilde{\xi}$ in $B_s^{(1)}$ satisfying $\|\eta\|_s < \gamma h$, $\|\eta_x\| < R_2$, $|\operatorname{Im} y_x| < K < 1$ and similar conditions for $\tilde{\eta}$ and $\tilde{\eta}_x$, we have the following estimates:*

$$(6.4) \quad \begin{aligned} &\|V_1\{\Omega, z\} - V_1\{\Omega, \tilde{z}\}\|_s \\ &\leq C(\gamma, R_2) \left\{ \left(\frac{\|y\|_s}{h} + \frac{\|y_x\|_s}{h} \right) \|\Omega - \tilde{\Omega}\|_s + \|\tilde{\Omega}\|_s \left(\frac{\|\eta - \tilde{\eta}\|_s}{h} + \frac{\|\eta_x - \eta_x\|_s}{h} \right) \right\}, \end{aligned}$$

$$(6.5) \quad \|V_2\{\Omega, z\} - V_2\{\Omega, \tilde{z}\}\|_s \leq C(\gamma, R_2) \left\{ \|\Omega - \tilde{\Omega}\|_s + \|\tilde{\Omega}\|_s \left(\frac{\|\eta - \tilde{\eta}\|_s}{h} + \frac{\|\eta_x - \tilde{\eta}_x\|_s}{h} \right) \right\},$$

$$(6.6) \quad \|C_h\{\eta\}\xi - C_h\{\tilde{\eta}\}\tilde{\xi}\|_s \leq \alpha C(\gamma, R_2)(\gamma + \|\eta_x\|_s)\|\xi - \tilde{\xi}\|_s,$$

$$(6.7) \quad \|C_h\{\eta\}\xi - C_h\{\tilde{\eta}\}\tilde{\xi}\|_s \leq \alpha C(\gamma, R_2)\|\xi\|_x \left(\frac{\|\eta - \tilde{\eta}\|_s}{h} + \frac{\|\eta_x - \tilde{\eta}_x\|_s}{h} \right),$$

where $C(\gamma, R_2)$ is uniformly bounded for $\gamma \in [0, \gamma_0]$ with $\gamma_0 < 1$ and $R_2 \leq R$, R arbitrary.

PROOF. We shall estimate the two terms of V_1 , referred as V_1^A and V_1^B separately. We also separate the contribution of short and large distances and write

$$V_1^A\{\Omega, y\} = U_1^{(1)}\{\Omega, y\} + U_1^{(2)}\{\Omega, y\},$$

where $(i = 1, 2)$

$$(6.8) \quad U_1^{(i)}\{\Omega, y\}(x+i\sigma) = -\frac{1}{2\pi} \int \frac{(y(x+i\sigma) - y(x'+i\sigma))(x'+i\sigma)}{(x-x')^2 + (y(x+i\sigma) - y(x'+i\sigma))^2} \theta_i(|x-x'|) dx'.$$

where $C(\gamma, R_2)$ is uniformly bounded for $\gamma \in [0, \gamma_0]$ with $\gamma_0 < 1$ and $R_2 \leq R$, R arbitrary.

PROOF. We shall estimate the two terms of V_1 , referred as V_1^A and V_1^B separately. We also separate the contribution of short and large distances and write

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where $(i = 1, 2)$

(6.8)

$$U_1^{(i)}\{\Omega, y\}(x + i\sigma) = -\frac{1}{2\pi} \int \frac{(y(x + i\sigma) - y(x' + i\sigma))(x' + i\sigma)}{(x - x')^2 + (y(x + i\sigma) - y(x' + i\sigma))^2} \theta_i(|x - x'|) dx'.$$

θ_1 is a C^∞ -function with absolute value smaller than one and compact support in $[-2h, 2h]$, $\theta_2 = 1 - \theta_1$. It is shown in [10] that

$$(6.9) \quad \|U_1^{(1)}\{\Omega, y\} - U_1^{(1)}\{\tilde{\Omega}, \tilde{y}\}\|_s \leq C(1 + R_2^2)(\|y_x\| \|\Omega - \tilde{\Omega}\|_s + \|\tilde{\Omega}\|_s \|y_x - \tilde{y}_x\|_s).$$

The introduction of the L^2 -norms of Ω and y in the estimate of the contribution from large distance is avoided by writing

$$(6.10) \quad |U_1^{(2)}\{\Omega, y\} - U_1^{(2)}\{\tilde{\Omega}, \tilde{y}\}|_s \leq C \left\{ \frac{|\eta|_s}{h} |\Omega - \tilde{\Omega}|_s + |\tilde{\Omega}|_s (1 + R_2^2) \frac{|\eta - \tilde{\eta}|_s}{h} \right\}$$

and

(6.11)

$$|\nabla U^{(2)}\{\Omega, y\} - \nabla U^{(2)}\{\tilde{\Omega}, \tilde{y}\}|_s \leq C(1 + R_2^2) \left\{ \frac{|\eta_x|_s}{h} |\Omega - \tilde{\Omega}|_s + |\tilde{\Omega}|_s \frac{|\eta_x - \tilde{\eta}_x|_s}{h} \right\}.$$

To estimate V_1^B we proceed as above and write

$$(6.12) \quad V_1^{(R)}\{\Omega, y\} = U_1^{(1)}\{\Omega, y\} + U_1^{(2)}\{\Omega, y\},$$

where

$$(6.13) \quad U_1^{(i)}\{\Omega, y\} = \frac{1}{2\pi} \int \frac{(y(x + i\sigma) + y(x' + i\sigma))\Omega(x' + i\sigma)}{(x - x')^2 + (y(x + i\sigma) + y(x' + i\sigma))^2} \theta_i(|x - x'|) dx'$$

with $\delta\Omega = \Omega - \tilde{\Omega}$, $\delta y = y - \tilde{y}$, $\delta\eta = \eta - \tilde{\eta}$; we have

$$(6.14) \quad \begin{aligned} & U_1^{(i)}\{\Omega, y\} - U_1^{(i)}\{\tilde{\Omega}, \tilde{y}\} \\ &= \frac{1}{2\pi} \int \theta_i(|x - x'|) \frac{y(x + i\sigma) + y(x' + i\sigma)\delta\Omega(x' + i\sigma)}{(x - x')^2 + (y(x + i\sigma) + y(x' + i\sigma))^2} dx' \\ &+ \int \theta_i(|x - x'|) \frac{(\delta y(x + i\sigma) + \delta y(x' + i\sigma))\tilde{\Omega}(x' + i\sigma)}{(x - x')^2 + (y(x + i\sigma) + y(x' + i\sigma))^2} dx' \\ &+ \int \theta_i(|x - x'|) \frac{(\tilde{y}(x + i\sigma) + \tilde{y}(x' + i\sigma))(\delta\eta(x + i\sigma) + \delta\eta(x' + i\sigma))}{[(x - x')^2 + (y(x + i\sigma) + y(x' + i\sigma))^2]} \\ &\quad \times \frac{((y + \tilde{y})(x + i\sigma) + (y + \tilde{y})(x' + i\sigma))\tilde{\Omega}(x' + i\sigma)}{[(x - x')^2 + (y(x + i\sigma) + y(x' + i\sigma))^2]} dx. \end{aligned}$$

For $|\eta|_s < \gamma h$, the denominator

$$(6.15) \quad D_+ = (x - x')^2 + (y(x + i\sigma) + y(x' + i\sigma))^2$$

is bounded from below by

$$(6.16) \quad |D_+| \geq h^2(1 - \gamma)^2$$

is the integral containing θ_1 and by

$$(6.17) \quad |D_+| \geq (x - x')^2 - 4\gamma^2 h^2$$

is the integral containing θ_2 . Consequently, for $\|\eta\|_s < \gamma h$ and $\|\tilde{\eta}\|_s < \gamma h$,

$$(6.18) \quad |U_1^{(1)}\{\Omega, y\} - U_1^{(1)}\{\tilde{\Omega}, \tilde{y}\}|_s \leq C \left\{ \frac{|\delta\Omega|_s}{(1 - \gamma)^2} + |\Omega|_s \frac{|\delta\eta|_s}{(1 - \gamma)^2 h} + |\Omega|_s \frac{|\delta\eta|_s}{(1 - \gamma)^4 h} \right\}$$

and

$$(6.19) \quad \begin{aligned} & |U_1^{(2)}\{\Omega, y\} - U_1^{(2)}\{\tilde{\Omega}, \tilde{y}\}|_s \\ & \leq C \left\{ |\delta\Omega|_s h \int \frac{dx}{(x - x')^2 - 4\gamma^2 h^2} + |\Omega|_s |\delta\eta|_s \int \frac{dx'}{(x - x')^2 - 4\gamma^2 h^2} \right. \\ & \quad \left. + |\Omega|_s h^2 |\delta\eta|_s \int_{|x - x'| > 2h} \frac{dx'}{[(x - x')^2 - 4\gamma^2 h^2]^2} \right\} \\ & \leq C \left\{ \frac{1}{\gamma} \ln \frac{1 + \gamma}{1 - \gamma} \left(|\delta\Omega|_s + \frac{|\delta\eta|_s}{h} |\Omega|_s \right) + \frac{1}{\gamma^3} \left(\frac{2\gamma}{1 - \gamma^2} - \ln \frac{1 + \gamma}{1 - \gamma} \right) \frac{|\delta\eta|_s}{h} |\Omega|_s \right\}. \end{aligned}$$

The constants

$$\frac{1}{\gamma} \ln \frac{1 + \gamma}{1 - \gamma} \quad \text{and} \quad \frac{1}{\gamma^3} \left(\frac{2\gamma}{1 - \gamma^2} - \ln \frac{1 + \gamma}{1 - \gamma} \right)$$

are uniformly bounded for $\gamma \in [0, \gamma_0]$ with $\gamma_0 < 1$.

To estimate the difference

$$(6.20) \quad \Delta = (V_1^B\{\Omega, y\} - V_1^B\{\tilde{\Omega}, \tilde{y}\})(x + i\sigma) - (V_i^B\{\Omega, y\}V_1^B\{\tilde{\Omega}, \tilde{y}\})(x' + i\sigma),$$

we first notice that

$$(6.21) \quad \pi\Omega(x + i\sigma) = \int_{-\infty}^{+\infty} \frac{2y(x + i\sigma)\Omega(x + i\sigma)}{(x - q)^2 + 4y^2(x + i\sigma)} dq.$$

The equality is obvious in the real domain. It extends to the complex domain because of the uniqueness of the analytic continuation. We then compute the difference Δ . Denoting

$$(6.22) \quad D_+\{y\}(x + i\sigma, q + i\sigma) = (x - q)^2 + (y(x + i\sigma) + y(q + i\sigma))^2$$

and

$$(6.23) \quad D_0\{y\}(x + i\sigma, q + i\sigma) = (x - q)^2 + 4y^2(x + i\sigma)^2$$

we write

$$(6.24) \quad \Delta = \sum_{i=1}^2 \Delta_1^{(i)} + \Delta_2 + \sum_{i=1}^2 \Delta_3^{(i)} + \Delta_4 + \sum_{i=1}^2 \Delta_5^{(i)} + \Delta_6,$$

where

$$(6.25) \quad \Delta_1^{(i)} = \frac{1}{2\pi} \int \theta_i(|x-q|) \left\{ \frac{(y(x+i\sigma) + y(q+i\sigma))\delta\Omega(q+i\sigma)}{D_+\{y\}(x+i\sigma, q+i\sigma)} - \frac{2y(x+i\sigma)\delta\Omega(x+i\sigma)}{D_0\{y\}(x+i\sigma, q+i\sigma)} \right\} dq \\ - \frac{1}{2\pi} \int \theta_i(|x-q|) \left\{ \frac{(y(x'+i\sigma) + y(q+i\sigma))\delta\Omega(q+i\sigma)}{D_+\{y\}(x'+i\sigma, q+i\sigma)} - \frac{2y(x'+i\sigma)\delta\Omega(x'+i\sigma)}{D_0\{y\}(x'+i\sigma, q+i\sigma)} \right\} dq,$$

$$(6.26) \quad \Delta_2 = -\frac{1}{2\pi}(\delta\Omega(x+i\sigma) - \delta\Omega(x'+i\sigma)),$$

$$(6.27) \quad \Delta_3^{(i)} = \frac{1}{2\pi} \int \theta_i(|x-q|) \left\{ \frac{(\delta y(x+i\sigma) + \delta y(q+i\sigma))\tilde{\Omega}(q+i\sigma)}{D_+\{y\}(x+i\sigma, q+i\sigma)} - \frac{2\delta y(x+i\sigma)\tilde{\Omega}(q+i\sigma)}{D_0\{y\}(x+i\sigma, q+i\sigma)} \right\} dq \\ - \frac{1}{2\pi} \int \theta_i(|x-q|) \left\{ \frac{(\delta y(x'+i\sigma) + \delta y(q+i\sigma))\tilde{\Omega}(q+i\sigma)}{D_+\{y\}(x'+i\sigma, q+i\sigma)} - \frac{2\delta y(x'+i\sigma)\tilde{\Omega}(q+i\sigma)}{D_0\{y\}(x'+i\sigma, q+i\sigma)} \right\} dq,$$

$$(6.28) \quad \Delta_4 = \frac{1}{2} \left(\frac{\delta\eta(x+i\sigma)}{y(x+i\sigma)} - \frac{\delta\eta(x'+i\sigma)}{y(x'+i\sigma)} \right),$$

$$(6.29) \quad \Delta_5^{(i)} = \frac{1}{2\pi} \int \theta_i(|x-q|) \left\{ \frac{(\tilde{y}(x+i\sigma) + \tilde{y}(q+i\sigma))(\delta\eta(x+i\sigma) + \delta\eta(q+i\sigma))}{D_+\{y\}(x+i\sigma, q+i\sigma)} \times \frac{((y+\tilde{y})(x+i\sigma) + (y+\tilde{y})(q+i\sigma))\tilde{\Omega}(q+i\sigma)}{D_+\{\tilde{y}\}(x+i\sigma, q+i\sigma)} - \frac{8\tilde{y}(x+i\sigma)\delta\eta(x+i\sigma)(y+\tilde{y})(x+i\sigma)\tilde{\Omega}(x+i\sigma)}{D_0\{y\}(x+i\sigma, q+i\sigma)D_0\{\tilde{y}\}(x+i\sigma, q+i\sigma)} \right\} dq \\ + \frac{1}{2\pi} \int \theta_i(|x'-q|) \left\{ \frac{(\tilde{y}(x'+i\sigma) + \tilde{y}(q+i\sigma))(\delta\eta(x'+i\sigma) + \delta\eta(q+i\sigma))}{D_+\{y\}(x'+i\sigma, q+i\sigma)} \times \frac{((y+\tilde{y})(x'+i\sigma) + (y+\tilde{y})(q+i\sigma))\tilde{\Omega}(q+i\sigma)}{D_+\{\tilde{y}\}(x'+i\sigma, q+i\sigma)} - \frac{8\tilde{y}(x'+i\sigma)\delta\eta(x'+i\sigma)(y+\tilde{y})(x+i\sigma)\tilde{\Omega}(x+i\sigma)}{D_0\{y\}(x+i\sigma, q+i\sigma)D_0\{\tilde{y}\}(x'+i\sigma, q+i\sigma)} \right\} dq.$$

$$(6.30) \quad \Delta_6 = 8 \int \left\{ \frac{y(x+i\sigma)\delta\eta(x+i\sigma)(y+\tilde{y})(x+i\sigma)\tilde{\Omega}(x+i\sigma)}{D_0\{y\}(x+i\sigma, q+i\sigma)D_0\{y\}(x+i\sigma, q+i\sigma)} - \frac{\tilde{y}(x'+i\sigma)\delta\eta(x'+i\sigma)(y+\tilde{y})(x+i\sigma)\tilde{\Omega}(x'+i\sigma)}{D_0\{y\}(x'+i\sigma, q+i\sigma)D_0\{\tilde{y}\}(x'+i\sigma, q+i\sigma)} \right\} dq.$$

Let us first assume that $|x - x'| < 2h$. In $\Delta_j^{(1)}$, we split the integration domain into the ball $\Sigma = \{q, |x - q| < 2|x - x'|\}$ and its complement $R^2 \setminus \Sigma$. Let $\delta_j^{(1)}$ and $\bar{\delta}_j^{(1)}$ be the corresponding contribution. We have

$$(6.31) \quad |\delta_1^{(1)}| + |\delta_3^{(1)}| + |\delta_5^{(1)}| \leq C|x - x'|^\alpha (\|\delta\Omega\|_s + \|\tilde{\Omega}\|_s \|\delta\eta\|_s / h)$$

and

$$(6.32) \quad |\bar{\delta}_1^{(1)}| + |\bar{\delta}_3^{(1)}| + |\bar{\delta}_5^{(1)}| \leq C|x - x'|^\alpha (\|\delta\Omega\|_s + \|\tilde{\Omega}\|_s \|\delta\eta\|_s / h).$$

On the other hand,

$$(6.33) \quad |\Delta_1^{(2)}| + |\Delta_3^{(2)}| + |\Delta_5^{(2)}| \leq |x - x'|^\alpha \left(\|\delta\eta\|_s + \frac{\|\delta\eta\|_s}{h} \right) \\ \times \left\{ \frac{1}{\gamma} \ln \frac{1+\gamma}{1-\gamma} + \frac{1}{\gamma^3} \left(\frac{2\gamma}{1-\gamma^2} - \ln \frac{\gamma+1}{1-\gamma} \right) \right. \\ \left. + \frac{1}{\gamma^4} \int_{|\mu|>1/\gamma} \frac{\mu d\mu}{(\mu^2-1)^3} + \frac{1}{\gamma^{5-\alpha}} \int_{|\mu|>1/\gamma} \frac{\mu^\alpha d\mu}{(\mu^2-1)^3} \right. \\ \left. + \frac{1}{\gamma^5} \int_{|\mu|>1/\gamma} \frac{\mu^2 d\mu}{(\mu^2-1)^4} + \frac{1}{\gamma^{5-\alpha}} \int_{|\mu|>1/\gamma} \frac{\mu^{2+\alpha} d\mu}{(\mu^2-1)^4} \right\}.$$

When $|x - x'| > 2h$, the two terms of $\Delta_j^{(i)}$ ($i = 1, 2$, $j = 1, 3, 5$) are bounded separately and we obtain the same upper bounds. On the other hand, we have

$$(6.34) \quad |\Delta_2| + |\Delta_4| \leq C(\|\delta\Omega\|_s + \|\tilde{\Omega}\|_s \|\delta\eta\|_s / (1-\gamma)h) |x - x'|^\alpha.$$

Noticing finally that

$$(6.35) \quad \Delta_6 = -\frac{1}{2} \left(\frac{\Omega(x+i\sigma)}{y(x+i\sigma)} \delta\eta(x+i\sigma) - \frac{\Omega(x+i\sigma)}{y(x'+i\sigma)} \delta\eta(x'+i\sigma) \right),$$

we obtain

$$(6.36) \quad \|V_1^B\{\Omega, y\} - V_1^B\{\tilde{\Omega}, y\}\|_s \leq C(\gamma) \left\{ \|\Omega - \tilde{\Omega}\|_s + \frac{\|\eta - \tilde{\eta}\|_s}{h} \|\Omega\|_s \right\},$$

where $C(\gamma)$ is uniformly bounded for all γ in $[0, \gamma_0]$ with $\gamma_0 < 1$.

Let us now turn to the estimates for V_2 . As previously, we write

$$(6.37) \quad V_2\{\Omega, y\} = U_2^{(1)}\{\Omega, y\} + U_2^{(2)}\{\Omega, y\}$$

with

$$(6.38) \quad U_2^{(i)}\{\Omega, y\}(x+i\sigma) = \frac{1}{2\pi} \int \theta_i(|x - x'|) \\ \times \left(\frac{x - x'}{(x - x')^2 + (y(x+i\sigma) - y(x'+i\sigma))^2} \right. \\ \left. - \frac{x - x'}{(x - x')^2 + (y(x+i\sigma) + y(x'+i\sigma))^2} \right) \Omega(x' + i\sigma) dx'.$$

Estimating the two terms of $U_2^{(1)}$ separately, we get, proceeding as previously

$$(6.39) \quad \|U_2^{(1)}\{\Omega, y\} - U_2^{(1)}\{\tilde{\Omega}, \tilde{y}\}\|_s \leq C(\gamma) \left(\|\delta\Omega\|_s + \frac{\|\delta\eta\|_s}{h} \|\tilde{\Omega}\|_s + \|\delta\eta\|_s \|\tilde{\Omega}\|_s \right),$$

where $C(\gamma)$ is uniformly bounded for $\gamma \in [0, \gamma_0]$, $\gamma_0 < 1$. For the contribution at large distance, we have to deal with the two terms of $U^{(2)}$ together in order to avoid the introduction of L^2 -norms:

$$(6.40) \quad U_2^{(2)}\{\Omega, y\}(x + i\sigma) = \frac{1}{2\pi} \int \theta_2(|x - x'|) \frac{4(x - x')y(x + i\sigma)y(x' + i\sigma)\Omega(x' + i\sigma)}{D_+\{y\}(x + i\sigma, x' + i\sigma)D_-\{y\}(x + i\sigma, x' + i\sigma)} dx',$$

where

$$D_-\{y\}(x + i\sigma, x' + i\sigma) = (x - x')^2 + (y(x + i\sigma) - y(x' + i\sigma))^2,$$

and $D_+\{y\}$ is defined in (6.22). We have

$$(6.41) \quad U_2^{(2)}\{\Omega, y\}(x + i\sigma) - U_2^{(2)}\{\tilde{\Omega}, \tilde{y}\}(x + i\sigma) = (d_1 + d_2 + d_3 + d_4 + d_5)(x + i\sigma)$$

with

$$(6.42) \quad d_1(x + i\sigma) = U^{(2)}\{\delta\Omega, y\}(x + i\sigma),$$

$$(6.43) \quad d_2(x + i\sigma) = \frac{1}{2\pi} \int \theta_2(|x - x'|) \frac{4(x - x')\delta\eta(x + i\sigma)y(x' + i\sigma)\tilde{\Omega}(x' + i\sigma)}{D_+\{y\}(x + i\sigma, x' + i\sigma)D_-\{y\}(x + i\sigma, x' + i\sigma)} dx',$$

$$(6.44) \quad d_3(x + i\sigma) = \frac{1}{2\pi} \int \theta_2(|x - x'|) \frac{4(x - x')\tilde{y}(x + i\sigma)\delta\eta(x' + i\sigma)\tilde{\Omega}(x' + i\sigma)}{D_+\{y\}(x + i\sigma, x' + i\sigma)D_-\{y\}(x + i\sigma, x' + i\sigma)} dx,$$

$$(6.45) \quad d_4(x + i\sigma) = \frac{1}{2\pi} \int \theta_2(|x - x'|) \frac{4(x - x')\tilde{y}(x + i\sigma)\tilde{y}(x' + i\sigma)\tilde{\Omega}(x' + i\sigma)(\delta\eta(x + i\sigma) + \delta\eta(x' + i\sigma))}{D_+\{y\}(x + i\sigma, x' + i\sigma)D_+\{\tilde{y}\}(x + i\sigma, x' + i\sigma)} \times \frac{((\eta + \tilde{\eta})(x + i\sigma) + (\eta + \tilde{\eta})(x' + i\sigma))}{D_-\{y\}(x + i\sigma, x' + i\sigma)} dx',$$

$$(6.46) \quad d_5(x + i\sigma) = \frac{1}{2\pi} \int \theta_2(|x - x'|) \frac{4(x - x')\tilde{y}(x + i\sigma)y(x' + i\sigma)\tilde{\Omega}(x' + i\sigma)(\delta\eta(x + i\sigma) - \delta\eta(x' + i\sigma))}{D_+\{\tilde{y}\}(x + i\sigma, x' + i\sigma)D_-\{y\}(x + i\sigma, x' + i\sigma)} \times \frac{((\eta + \tilde{\eta})(x + i\sigma) - (\eta + \tilde{\eta})(x' + i\sigma))}{D_-\{\tilde{y}\}(x + i\sigma, x' + i\sigma)} dx.$$

For $|\operatorname{Im} y_x| < K < 1$ and $|\eta|_s < \gamma h$ ($\gamma \leq \gamma_0 < 1$), we have

$$(6.47) \quad |d_1| + |d_2| + |d_3| \leq C \left(|\delta\eta|_s + |\Omega|_s \frac{|\delta\eta|_s}{h} \right) \frac{1}{\gamma^2} \ln(1 - \gamma^2)$$

and

$$(6.48) \quad |d_4| + |d_5| \leq C |\Omega|_s \frac{|\delta\eta|_s}{h} \left(\frac{1}{4} \ln(1 - \gamma^4) + \frac{1}{\gamma^2} \ln(1 - \gamma^2) \right).$$

Thus,

$$(6.49) \quad |U_2^{(2)}\{\Omega, y\} - U_2^{(2)}\{\tilde{\Omega}, \tilde{y}\}| \leq C(\gamma) \left\{ \|\Omega - \tilde{\Omega}\|_s + \frac{\|\delta\eta\|_s}{h} \|\tilde{\Omega}\|_s \right\},$$

where $C(\gamma)$ is uniformly bounded for $\gamma \in [0, \gamma_0]$, $\gamma_0 < 1$. To estimate the difference $d_i(x + i\sigma) - d_i(x' + i\sigma)$ ($i = 1, 2, \dots, 5$), we write

$$\begin{aligned}
 (6.50) \quad d_1(x + i\sigma) &= \frac{1}{2\pi} \int \theta_2(|x - q|) \left\{ \frac{4(x - q)y(x + i\sigma)y(q + i\sigma)\delta\Omega(q + i\sigma)}{D_+\{y\}(x + i\sigma, q + i\sigma)D_-\{y\}(x + i\sigma, q + i\sigma)} \right. \\
 &\quad \left. - \frac{4(x - q)y^2(x + i\sigma)\delta\Omega(x + i\sigma)}{D_0\{y\}(x + i\sigma, q + i\sigma)(x - q)^2(1 + y_x^2(x + i\sigma))} \right\} dq \\
 &= \frac{1}{2\pi} \int 4\theta_2(x - q) \left\{ \frac{(x - q)y(x + i\sigma)y(q + i\sigma)\delta\Omega(q + i\sigma) - y(x + i\sigma)\delta\Omega(x + i\sigma)}{D_+\{y\}(x + i\sigma, q + i\sigma)D_-\{y\}(x + i\sigma, q + i\sigma)} \right\} \\
 &\quad + \frac{1}{2\pi} \int 4\theta_2(|x - q|) \frac{(x - q)y^2(x + i\sigma)\delta\Omega(x + i\sigma)}{D_-\{y\}(x + i\sigma, q + i\sigma)} \\
 &\quad \times \left\{ \frac{(y(x + i\sigma) - y(q + i\sigma))(3y(x + i\sigma) + y(q + i\sigma))}{D_0\{y\}(x + i\sigma, q + i\sigma, q + i\sigma)D_+\{y\}(x + i\sigma, q + i\sigma)} \right\} dq \\
 &\quad + \frac{1}{2\pi} \int 4\theta_2(|x - q|) \frac{y^2(x + i\sigma)\delta\Omega(x + i\sigma)}{(x - q)D_0\{y\}(x + i\sigma, q + i\sigma)} \\
 &\quad \times \left\{ \frac{((x - q)y_x(x + i\sigma) - (y(x + i\sigma) - y(q + i\sigma)))}{D_-\{y\}(x + i\sigma, q + i\sigma)} \right. \\
 &\quad \times \left. \frac{((x - q)y_x(x + i\sigma) + y(x + i\sigma) - y(q + i\sigma))}{(1 + y_x^2(x + i\sigma))} \right\} dq
 \end{aligned}$$

and similar expressions for $d_2, \dots, d_5$.

When estimating $d_i(x + i\sigma) - d_i(x' + i\sigma)$, we separate, as previously, the contributions $|x - x'| < 2h$ and $|x - x'| > 2h$ and proceed as above. We obtain

$$\|U_2^{(2)}\{\Omega, y\} - U_2^{(2)}\{\tilde{\Omega}, \tilde{y}\}\|_s \leq C(\gamma) \left\{ \|\Omega - \tilde{\Omega}\|_s + \frac{\|\delta\eta\|_s}{h} \|\tilde{\Omega}\|_s + \left\| \frac{\delta\eta_x}{h} \right\|_s \|\tilde{\Omega}\|_s \right\}.$$

This concludes the proof of (6.4) and (6.5).

Let us now turn to the operator A . Noticing that the kernels $\mathcal{G}$ and $d\mathcal{G}/dx$ belongs to $L^1(R + i\sigma)$, it is sufficient to estimate the operator $C_h\{\eta\}\xi$. Let us rewrite $C_h\{\eta\}$ in the form

$$\begin{aligned}
 C_h\{\eta\}(x + i\sigma) &= \frac{\alpha}{2\pi} \int \frac{\eta(x + i\sigma) + \eta(q + i\sigma)}{D_+\{y\}(x + i\sigma, q + i\sigma)} \xi(q + i\sigma) dq \\
 &\quad - \int \frac{\eta(x + i\sigma) - \eta(x' + i\sigma)}{D_-\{y\}(x + i\sigma, q + i\sigma)} \xi(q + i\sigma) dq \\
 &\quad + \frac{\alpha}{2\pi} \int 2h \frac{(\eta(x + i\sigma) + \eta(x' + i\sigma))(2h + y(x + i\sigma) + y(x' + i\sigma))}{D_+\{y\}(x + i\sigma, q + i\sigma)((x - q)^2 + 4h^2)} \xi(q + i\sigma) dq \\
 &\quad + \frac{\alpha}{2\pi} \int \eta_x(x + i\sigma) \frac{4(x_q)y(x + i\sigma)y(q + i\sigma)\xi(q + i\sigma)}{D_+\{y\}(x + i\sigma, q + i\sigma)D_-\{y\}(x + i\sigma, q + i\sigma)} dq.
 \end{aligned}$$

Using the upper bounds of V_1 and V_2 obtained previously, we get, for $\|\eta\|_s \leq \gamma h$ and $\|\eta_x\| < R_2$,

$$(6.53) \quad \|C_h\{\eta\}\xi - C_h\{\tilde{\eta}\}\xi\|_s \leq \alpha C(\gamma, R_2) \{\gamma \|\xi - \tilde{\xi}\|_s + \|\eta_x\|_s \|\xi - \tilde{\xi}\|_s\},$$

$$(6.54) \quad \|C_h\{\eta\}\xi - C_h\{\tilde{\eta}\}\xi\|_s \leq \alpha C(\gamma, R_2) \|\xi\|_s \left(\frac{\|\eta - \tilde{\eta}\|_s}{h} + \frac{\|\eta_x - \tilde{\eta}_x\|_s}{h} \right),$$

where $C(\gamma, R_2)$ is uniformly bounded for $\gamma \in [0, \gamma_0]$, $\gamma_0 < 1$, and $R_2 \leq R$, R arbitrary.

THEOREM 6.1. *There exists a constant k_0 , such that for initial conditions $(y_0 = h + \eta_0, dy_0/dx, \Omega_0)$ whose analytic continuation belongs to $(B_{s_0}^{(1)})^3$ with the conditions $|\operatorname{Im}(dy_0/dx)|_s < K < 1$, $\|dy_0/dx\|_s < \gamma h$, $\gamma \leq \gamma_0 < 1$ and $\alpha(\gamma + \|dy_0/dx\|_s) < k_0$, there exists a constant a such that, for $|t| < a(s_0 - s)$, the system (2.28) has a unique solution (y, y_x, Ω) which is an analytic function of t with value in $(B_s^{(1)})^3$.*

b. *Three-dimensional flows.* The operators V and A defined in (3.25), (3.39) and (3.40) are analytically continued to the strip $b_1 = \{(\bar{x} + i\bar{\sigma}), \bar{x} \in R^2, |0| < s\}$ by replacing $\bar{x}$ and $\bar{x}'$ by $\bar{x} + i\bar{\sigma}$ and $\bar{x}' + i\bar{\sigma}$ in the formulas (3.25) and (3.38)–(3.40).

The denominators will not vanish if $|\operatorname{Im} \nabla z|_s < K < 1$ and $|\eta|_s < \gamma h$, where γ is a positive number strictly smaller than one.

PROPOSITION 6.2. *For $\eta, \nabla \eta, \Omega, \xi$ and $\tilde{\eta}, \nabla \tilde{\eta}, \tilde{\Omega}, \tilde{\xi}$ in $B_s^{(1)}$ satisfying $\|\eta\|_s < \gamma h$, $\|\nabla \eta\|_s < R_2$, $|\operatorname{Im} \nabla \eta|_s < K < 1$, and similar conditions for $\tilde{\eta}$ and $\nabla \tilde{\eta}$, we have the following estimates ($z = h + \eta$, $\tilde{z} = h + \tilde{\eta}$):*

$$(6.55) \quad \|V\{\Omega, z\} - V\{\tilde{\Omega}, \tilde{z}\}\|_s \leq C(\gamma, R_2)(1 + \|z\|_s/h + \|\nabla \eta\|_s/h \|\Omega - \tilde{\Omega}\|_s \\ + \|\tilde{\Omega}\|_s \{\|\eta - \tilde{\eta}\|_s/h + \|\nabla(\eta - \tilde{\eta})\|_s/h\},$$

$$(6.56) \quad \|A_j\{z\}\xi - A_j\{\tilde{z}\}\tilde{\xi}\|_s \leq C(\gamma, R_2)(\gamma + \|\nabla \eta\|_s)\|\xi - \tilde{\xi}\|_s,$$

$$(6.57) \quad \|A_j\{z\}\xi - A_j\{\tilde{z}\}\tilde{\xi}\|_s \leq C(\gamma, R_2)\|\xi\|_s (\|\eta - \tilde{\eta}\|_s/h + \|\nabla(\eta - \tilde{\eta})\|_s/h).$$

Let us define

$$(6.58) \quad D_{\pm}\{z\}(\bar{x} + i\bar{\sigma}, x'_i\bar{\sigma}) = \{(\bar{x} - \bar{x}')^2 + (z(\bar{x} + i\bar{\sigma}) \pm z(\bar{x}' + i\bar{\sigma}))^2\}^{3/2},$$

$$(6.59) \quad D_0\{z\}(\bar{x} + i\bar{\sigma}, \bar{x}' + i\bar{\sigma}) = \{(\bar{x} - \bar{x}')^2 + 4z^2(\bar{x} + i\bar{\sigma})\}^{3/2}.$$

To estimate V , we separately consider the operators

$$(6.60) \quad U_j^{(i)}\{\Omega, z\}(\bar{x} + i\bar{\sigma}) \\ = \int \theta_i(|\bar{x} - \bar{x}'|) \left\{ \frac{x_j - x'_j}{D_+\{z\}(\bar{x} + i\bar{\sigma}, \bar{x}' + i\bar{\sigma})} - \frac{x_j - x'_j}{D_+\{z\}(\bar{x} + i\bar{\sigma}, \bar{x}' + i\bar{\sigma})} \right\} \Omega(\bar{x} + i\bar{\sigma}) d\bar{x}',$$

$$(6.61) \quad W^{(i)}\{\Omega, z\}(\bar{x} + i\bar{\sigma}) \\ = \int \theta_i(|\bar{x} - \bar{x}'|) \left\{ \frac{z(\bar{x} + i\bar{\sigma}) - z(\bar{x}' + i\bar{\sigma})}{D_-\{z\}(\bar{x} + i\bar{\sigma}, \bar{x}' + i\bar{\sigma})} - \frac{z(\bar{x} + i\bar{\sigma}) + z(\bar{x}' + i\bar{\sigma})}{D_+\{z\}(\bar{x} + i\bar{\sigma}, \bar{x}' + i\bar{\sigma})} \right\} \Omega(\bar{x}' + i\bar{\sigma}) d\bar{x}',$$

where the functions θ_i defined in (6.8) separate the contributions at short and large distances. Like in two dimensions, the two terms of $U_j^{(1)}$ ($j = 1, 2$) and of $W^{(1)}$ and $W^{(2)}$ are estimated separately. We have

$$(6.62) \quad \|U_j^{(1)}\{\Omega, z\} - U_j^{(1)}\{\tilde{\Omega}, \tilde{z}\}\|_s \\ \leq C(\gamma) \left\{ \left(\frac{\|z\|_s}{h} + \frac{\|\nabla \eta\|_s}{h} \right) \|\Omega - \tilde{\Omega}\|_s + \frac{\|\delta \eta\|_s}{h} \|\tilde{\Omega}\|_s + \|\tilde{\Omega}\|_s \|\nabla \delta \eta\|_s \right\}.$$

The first term of $W^{(i)}$, denoted by $W_1^{(i)}$, is estimated like in [10]:

$$(6.63) \quad \|W_1^{(i)}\{\Omega, z\} - W_1^{(i)}\{\tilde{\Omega}, z\}\|_s \\ \leq C(R_2) \left\{ \left(\frac{\|\delta\eta\|_s}{h} + \frac{\|z\|_s}{h} \right) \|\Omega - \tilde{\Omega}\|_s \right. \\ \left. + \|\tilde{\Omega}\|_s \left(\frac{\|\nabla(\eta - \tilde{\eta})\|_s}{h} + \|\eta - \tilde{\eta}\|_s/h \right) \right\}.$$

In the second term of $W^{(i)}$, denoted by $W_2^{(i)}$, we use for $|\eta|_s < \gamma h$,

$$(6.64) \quad |D_+| \geq (1 - \gamma)^3 h^3$$

in $W_2^{(1)}$ and

$$(6.65) \quad |D_+| \geq ((\vec{x} - \vec{x}')^2 - 4\gamma^2 h^2)^{3/2}$$

in $W_2^{(2)}$. We thus get

$$(6.66) \quad |W_2^{(1)}\{\Omega, z\} - W_2^{(1)}\{\tilde{\Omega}, \tilde{z}\}|_s \\ \leq C \left\{ \frac{|z|_s}{h(1 - \gamma)^3} |\delta\Omega|_s + \frac{|\delta\eta|_s}{h(1 - \gamma)^3} |\Omega|_s + \frac{|\delta\eta|_s}{h(1 - \gamma)^7} |\Omega|_s \right\}$$

and

$$(6.67) \quad |W_2^{(2)}\{\Omega, z\} - W_2^{(2)}\{\tilde{\Omega}, \tilde{z}\}|_s \leq C \{ |\delta\Omega|_s |z|_s + |\Omega|_s |\delta\eta|_s \} \int_{\rho > 2h} \frac{\rho d\rho}{(\rho^2 - 4\gamma^2 h^2)^{3/2}} \\ + C |\Omega|_s |\delta\eta|_s h^2 \int_{\rho > 2h} \frac{(\rho^2 + 4h^2) \rho d\rho}{(\rho^2 - 4\gamma^2 h^2)^{3/2}} \\ \leq \frac{C}{(1 - \gamma^2)^{1/2}} \left(|\delta\eta|_s \frac{|z|_s}{h} + |\Omega|_s \frac{|\delta\eta|_s}{h} \right) \\ + \frac{C}{(1 - \gamma^2)^2} |\Omega|_s \frac{|\delta\eta|_s}{h}.$$

To estimate the difference,

$$(6.68) \quad \Delta = (W_2^{(i)}\{\Omega, z\} - W_2^{(i)}\{\tilde{\Omega}, \tilde{z}\})(\vec{x} + i\vec{\sigma}) - (W_2^{(i)}\{\Omega, z\} - W_2^{(i)}\{\tilde{\Omega}, \tilde{z}\})(\vec{x}' + i\vec{\sigma}).$$

We notice that

$$(6.69) \quad \int_0^\infty \frac{2z(\vec{x} + i\vec{\sigma})\Omega(\vec{x} + i\vec{\sigma})}{(\rho^2 + 4z^2(\vec{x} + i\vec{\sigma}))^{3/2}} \rho d\rho = 2\pi\Omega(\vec{x} + i\vec{\sigma}).$$

We then rewrite the difference Δ like in (6.24):

$$(6.70) \quad \Delta = \sum_{i=1}^2 \Delta_1^{(i)} + \Delta_2 + \sum_{i=1}^2 \Delta_3^{(i)} + \Delta_4 + \sum_{i=1}^2 \Delta_5^{(i)} + \Delta_6,$$

where

$$(6.71) \quad \Delta_1^{(i)} = \int \theta_i(|\vec{x} - \vec{q}|) \left\{ \frac{(z(\vec{x} + i\vec{\sigma}) + z(\vec{q} + i\vec{\sigma}))\delta\Omega(\vec{q} + i\vec{\sigma})}{D_+\{z\}(\vec{x} + i\vec{\sigma}, \vec{q} + i\vec{\sigma})} - \frac{2z(\vec{x} + i\vec{\sigma})\delta\eta(\vec{q} + i\vec{\sigma})}{D_0\{z\}(\vec{x} + i\vec{\sigma}, \vec{q} + i\vec{\sigma})} \right\} d\vec{q} \\ - \int \theta_i(|\vec{x}' - \vec{q}|) \left\{ \frac{(z(\vec{x}' + i\sigma) + z(q + i\sigma))\delta\Omega(\vec{q} + i\vec{\sigma})}{D_+\{z\}(\vec{x}' + i\sigma, q + i\sigma)} - \frac{2z(\vec{x}' + i\vec{\sigma})\delta\Omega(\vec{q} + i\vec{\sigma})}{D_0\{z\}(\vec{x}' + i\vec{\sigma}, \vec{q} + i\vec{\sigma})} \right\} d\vec{q},$$

$$(6.72) \quad \Delta_2 = -\pi(\delta\Omega(\vec{x} + i\vec{\sigma}) - \delta\Omega(\vec{x}' + i\vec{\sigma})),$$

$$(6.73) \quad \Delta_3^{(i)} = \int \theta_i(|x - q|) \left\{ \frac{(\delta z(\vec{x} + i\vec{\sigma}) + \delta z(\vec{q} + i\vec{\sigma}))\tilde{\Omega}(\vec{q} + i\vec{\sigma})}{D_+\{z\}(\vec{x} + i\vec{\sigma}, \vec{q} + i\vec{\sigma})} - \frac{2\delta z(\vec{x} + i\vec{\sigma})\tilde{\Omega}(\vec{x} + i\vec{\sigma})}{D_0\{z\}(\vec{x} + i\sigma, \vec{q} + i\vec{\sigma})} \right\} d\vec{q} \\ - \int \theta_i(|x - q|) \left\{ \frac{(\delta z(\vec{x}' + i\vec{\sigma}) + \delta z(\vec{q} + i\vec{\sigma}))\tilde{\Omega}(q + i\vec{\sigma})}{D_+\{z\}(\vec{x}' + i\vec{\sigma}, \vec{q} + i\vec{\sigma})} - \frac{2\delta z(\vec{x}' + i\vec{\sigma})\tilde{\Omega}(\vec{x} + i\vec{\sigma})}{D_0\{z\}(\vec{x}' + i\vec{\sigma}, \vec{q} + i\vec{\sigma})} \right\} dq,$$

$$(6.74) \quad \Delta_4 = \left(\frac{\delta\eta(\vec{x} + i\vec{\sigma})}{z(\vec{x} + i\vec{\sigma})} \tilde{\Omega}(\vec{x} + i\vec{\sigma}) - \frac{\delta\eta(\vec{x}' + i\vec{\sigma})}{z(\vec{x}' + i\vec{\sigma})} \tilde{\Omega}(x + i\sigma) \right),$$

$$(6.75) \quad \Delta_5^{(i)} = \int \theta_i(|\vec{x} - \vec{q}|) \left\{ (\tilde{z}(\vec{x} + i\vec{\sigma}) + \tilde{z}(\vec{q} + i\vec{\sigma})) \left(\frac{1}{D_+\{z\}(\vec{x} + i\vec{\sigma}, \vec{q} + i\vec{\sigma})} - \frac{1}{D_+\{\tilde{z}\}(\vec{x} + i\vec{\sigma}, \vec{q} + i\vec{\sigma})} \right) \tilde{\Omega}(\vec{q} + i\sigma) \right. \\ \left. - 2\tilde{z}(\vec{x} + i\vec{\sigma}) \left(\frac{1}{D_0\{z\}(\vec{x} + i\vec{\sigma}, \vec{q} + i\vec{\sigma})} - \frac{1}{D_0\{\tilde{z}\}(\vec{x} + i\vec{\sigma}, \vec{q} + i\vec{\sigma})} \right) \tilde{\Omega}(x + i\sigma) \right\} d\vec{q} \\ - \int \theta_i(|\vec{x}' - \vec{q}|) \left\{ (z(\vec{x}' + i\vec{\sigma}) + z(\vec{q} + i\vec{\sigma})) \left(\frac{1}{D_+\{z\}(\vec{x}' + i\vec{\sigma}, \vec{q} + i\vec{\sigma})} - \frac{1}{D_+\{\tilde{z}\}(\vec{x}' + i\vec{\sigma}, \vec{q} + i\vec{\sigma})} \right) \tilde{\Omega}(q + i\sigma) \right. \\ \left. - 2\tilde{z}(\vec{x}' + i\vec{\sigma}) \left(\frac{1}{D_0\{z\}(\vec{x}' + i\vec{\sigma}, \vec{q} + i\vec{\sigma})} - \frac{1}{D_0\{\tilde{z}\}(\vec{x}' + i\vec{\sigma}, \vec{q} + i\vec{\sigma})} \right) \tilde{\Omega}(\vec{x}' + i\vec{\sigma}) \right\} d\vec{q},$$

$$(6.76) \quad \Delta_6 = \frac{\tilde{\Omega}(\vec{x} + i\vec{\sigma})}{z(\vec{x} + i\vec{\sigma})} \delta\eta(\vec{x} + i\vec{\sigma}) - \frac{\tilde{\Omega}(x' + i\sigma)}{z(\vec{x}' + i\vec{\sigma})} \delta\eta(\vec{x} + i\vec{\sigma}) - \delta\eta(\vec{x} + i\vec{\sigma}).$$

We obtain

$$(6.77) \quad \|W_2\{\Omega, z\} - W_2\{\tilde{\Omega}, \tilde{z}\}\|_s \leq C(\gamma, R_2) \|\delta\eta\|_s + \|\Omega\|_s \|\delta\eta\|_s/h,$$

where $C(\gamma, R_2)$ is a constant uniformly bounded for $\gamma \in [0, \gamma_0]$, $\gamma_0 < 1$, and $R_2 < R$, R arbitrary.

To estimate $U_j^{(2)}$, we write

$$(6.78) \quad U_j^{(2)}\{\Omega, z\}(\vec{x} + i\vec{\sigma}) = \int \theta_2(|\vec{x} - \vec{x}'|) \frac{(x_j - x'_j)(D_-\{z\} - D_+\{z\})(\vec{x} + i\vec{\sigma}, \vec{x}' + i\vec{\sigma})}{D_+\{z\}(\vec{x} + i\vec{\sigma}, \vec{x}' + i\vec{\sigma})D_-\{z\}(\vec{x} + i\vec{\sigma}, \vec{x}' + i\vec{\sigma})} \times \Omega(\vec{x}' + i\vec{\sigma}) d\vec{x}'$$

and we use

$$(6.79) \quad \frac{|D_+\{z\} - D_-\{z\}|}{|D_+\{z\}D_-\{z\}|} \leq h^2 \frac{\{2|\vec{x} - \vec{x}'|^2 + 2h^2 + C|x - x'|(|\vec{x} - \vec{x}'|^2 + 4h^2)^{1/2}\}}{|x - x'|^3(|x - x'|^2 - 4\gamma^2 h^2)^2}.$$

Thus

$$(6.80) \quad |U_j^{(2)}\{\delta\Omega, z\}| \leq c|\delta\Omega|_s h^2 \left\{ \int_{\rho > 2h} \frac{\rho d\rho}{(\rho^2 - 4\gamma^2 h^2)^2} + h^2 \int_{\rho > 2h} \frac{\rho d\rho}{\rho^2(\rho^2 - 4\gamma^2 h^2)^2} + h \int_{\rho > 2h} \frac{\rho d\rho}{\rho(\rho^2 - 4\gamma^2 h^2)^2} \right\} \leq |\delta\eta|_s \frac{1}{(1 - \gamma^2)}.$$

Similarly,

$$(6.81) \quad |U_j^{(2)}\{\Omega, z\} - U_j^{(2)}\{\Omega, \tilde{z}\}|_s \leq C(R_2)|\Omega|_2 \left\{ \frac{1}{1 - \gamma^2} \frac{|\delta\eta|_s}{h} + \frac{1}{(1 - \gamma^2)^{3/2}} \frac{|\delta\eta|_s}{h} + \frac{1}{(1 - \gamma^2)^2} \frac{|\delta\eta|_s}{h} \right\}.$$

To estimate

$$(U_j^{(2)}\{\Omega, z\} - U_j^{(2)}\{\tilde{\Omega}, \tilde{z}\})(\vec{x} + i\vec{\sigma}) - (U_j^{(2)}\{\Omega, z\} - U_j^{(2)}\{\tilde{\Omega}, \tilde{z}\})(\vec{x}' + i\vec{\sigma}),$$

we rewrite $U_j^{(2)}\{\Omega, z\}(\vec{x} + i\vec{\sigma})$ in the form

$$(6.82) \quad U_j^{(2)}\{\Omega, z\}(\vec{x} + i\vec{\sigma}) = \int \theta_2(|x - q|) \left\{ \frac{(x_j - q_j)(D_-\{z\} - D_+\{z\})(\vec{x} + i\vec{\sigma}, q + i\vec{\sigma})}{D_+\{z\}(\vec{x} + i\vec{\sigma}, q + i\vec{\sigma})D_-\{z\}(\vec{x} + i\vec{\sigma}, q + i\vec{\sigma})} - (x_j - q_j)\Omega(\vec{x} + i\vec{\sigma}) \right. \\ \left. \times \frac{\{|\vec{x} - \vec{q}|^3(1 + (\vec{x} - \vec{q})/|\vec{x} - \vec{q}| \cdot \nabla z(\vec{x} + i\vec{\sigma}))^{3/2} - D_0\{z\}(\vec{x} + i\vec{\sigma}, q + i\vec{\sigma})\}}{D_0\{z\}(\vec{x} + i\vec{\sigma}, q + i\vec{\sigma})|x - q|^3(1 + (\vec{x} - \vec{q})/|\vec{x} - \vec{q}| \cdot \nabla z(\vec{x} + i\vec{\sigma}))^{3/2}} \right\} d\vec{q},$$

where the last integral vanishes by symmetry. After lengthy but straightforward calculations, we get

$$(6.83) \quad \|U_j^{(2)}\{\Omega, z\} - U_j^{(2)}\{\tilde{\Omega}, \tilde{z}\}\|_s \leq c(\gamma, R_2) \left\{ \|\Omega - \tilde{\Omega}\|_s \frac{\|\delta\eta\|_s}{h} \frac{\|\nabla\delta\eta\|_s}{h} \right\}.$$

This completes the proof of (6.55).

The kernel $\mathcal{G}$, defined in (3.43), and its gradient belong to $L^1(R^2 + i\sigma)$. It is thus sufficient to estimate the operators $A_j\{z\}\xi$ for $j = 1, 2, 3$. These estimates follow from those on $V\{\Omega, z\}$. Thus,

$$(6.84) \quad \|A_j\{z\}\xi - A_j\{\tilde{z}\}\xi\|_s \leq \alpha C(\gamma, R_2)(\gamma + \|\nabla\eta\|_s)\|\xi - \tilde{\xi}\|_s,$$

$$(6.85) \quad \|A_j\{z\}\xi - A_j\{\tilde{z}\}\xi\|_s \leq \alpha C(\gamma, R_2)\|\xi\|_s \left(\frac{\|\eta - \tilde{\eta}\|_s}{h} + \frac{\|\nabla(\eta - \tilde{\eta})\|_s}{h} \right).$$

To estimate the second term of (3.42), we proceed as in §5 and get the same estimates (5.19)–(5.21) with the norm $\|\cdot\|_s$ replaced by the Hölder norms $\|\cdot\|$. This leads to

THEOREM 6.2. *There exists a constant k_0 such that for initial conditions ($z_0 = h + \eta + 0, \nabla z_0, \Omega_0$) whose analytic continuation belongs to $B_{s_0}^{(1)} \times (B_{s_0}^{(1)})^2 \times (B_{s_0}^{(1)})^3$ with the conditions $|\operatorname{Im} \nabla z_0|_s < K < 1$, $\|\eta_0\|_s < \gamma h$, $\gamma \leq \gamma_0 < 1$, and*

$$\alpha\{\gamma + \|\nabla\eta\|_s\} < k_0,$$

there exists a constant a , such that for $|t| < a(s_0 - s)$, the system (3.42) has a unique solution $(z, \nabla z, \Omega)$ which is an analytic function of t with values in $B_{s_0}^{(1)} \times (B_{s_0}^{(1)})^2 \times (B_{s_0}^{(1)})^3$.

REMARK. In the presence of a bottom, the initial interface perturbation is not required to vanish at infinity as it is the case when the Rayleigh-Taylor (or the Kelvin-Helmholtz) problem is considered in the entire space. The reason is the faster decay of the gradient of the Green function of the Poisson equation which relates a divergence free velocity and vorticity. This insures integral-convergence without additional assumptions. A similar situation is encountered in the proof of existence in the large of a unique solution to the two-dimensional Euler equation with smooth initial data (Hölder continuous vorticity) (Wolibner [16], Kato [17]). In the entire space, the initial vorticity is required to be bounded in $L^1(R^2)$ (Bardos and Benachour [18]). This condition is relaxed when the flow is considered in half a plane or a strip (Sulem [19]).

7. Open problems. The existence theorems presented in §§5 and 6 assume an initial interface with sufficiently small corrugations. One can, however, notice in two dimensions that, defining $\mu(x, t)$ as a primitive of $\Omega(x, t)$, (2.19)(b) may be written in the form

$$\frac{\partial \mu}{\partial t}(x, t) + \alpha \int \frac{\partial G}{\partial x'}(x, x') \frac{\partial \mu}{\partial t}(x', t) dx' = F(x, t).$$

When the problem is considered in the real domain, the operator

$$\mathcal{A} \frac{\partial \mu}{\partial t}(x) = \int \frac{\partial G}{\partial x'}(x, x') \frac{\partial \mu}{\partial t}(x') dx'$$

has all its eigenvalues with a modulus strictly larger than one. This property is a consequence of the irrotationality of the flow in the two domains separated by the interface [20, 21]. For $\alpha \leq 1$, the operator $1 + \alpha \mathcal{A}$ is thus invertible. However, the property is not necessarily preserved when the equations are continued to the complex domain if the norm of $\alpha \mathcal{A}$ is not smaller than 1.

Another questions concerns the shallow water limit [22] for the Rayleigh-Taylor problem in the presence of a horizontal bottom. It corresponds to the situation where $t = \varepsilon^{-1/2}\tilde{t}$, $y(x, t) = \varepsilon y^{(\varepsilon)}(x, t)$ and $\Omega(x, t) = \varepsilon^{1/2}\Omega^{(\varepsilon)}(x, t)$ with $\varepsilon \rightarrow 0$. One can show that if $y^{(\varepsilon)}$ and $\Omega^{(\varepsilon)}$ tend uniformly to $\eta^{(0)}$ and $\Omega^{(0)}$, then $\tilde{V}_1 = \varepsilon^{-1/2}V_1 \rightarrow \Omega^{(0)}$ and $\tilde{V}_2 = \varepsilon^{-3/2}V_2 \rightarrow \partial(\Omega^{(0)}y^{(0)})/\partial x + y^{(0)}\partial\Omega^{(0)}/\partial x$. The equations of motion then reduce to

$$(7.1) \quad \frac{\partial y^{(0)}}{\partial t} + \frac{\partial}{\partial x}(\Omega^{(0)}y^{(0)}) = 0, \quad \frac{\partial \Omega^{(0)}}{\partial t} + \frac{\partial}{\partial x} \left(\frac{\Omega^{(0)2}}{2} + \frac{2\alpha}{\alpha+1}gy^{(0)} \right) = 0,$$

where, in the shallow water limit, $\Omega^{(0)}$ identifies with the rescaled horizontal component of the velocity jump $\varepsilon^{-1/2}[u]$ across the interface.

Similarly, in three dimensions, if $z^{(\varepsilon)}(x, y, t) = \varepsilon z(x, y, t)$ and $\Omega^{(\varepsilon)}(x, y, t) = \varepsilon^{1/2}\Omega(x, y, t)$ have uniform limits $z^{(0)}$ and $\Omega^{(0)}$ when $\varepsilon \rightarrow 0$, then $\tilde{V}_1 = \varepsilon^{1/2}V_1 \rightarrow -\Omega^{(0)}$, $\tilde{V}_2 = -\varepsilon^{1/2}V_2 \rightarrow \Omega_1^{(0)}$ and

$$\tilde{V}_3 = \varepsilon^{-3/2}V_3 \rightarrow \frac{1}{2} \left\{ \frac{\partial}{\partial x} \left(z^{(0)}\Omega_2^{(0)} \right) + z^{(0)}\frac{\partial \Omega_2^{(0)}}{\partial x} + \frac{\partial}{\partial y} \left(z^{(0)}\Omega_1^{(0)} \right) + z^{(0)}\frac{\partial \Omega_1^{(0)}}{\partial y} \right\}.$$

Noticing that in the shallow water limit $\Omega_1^{(0)} = [u_2^{(0)}]$ and $\Omega_2^{(0)} = -[u_1^{(0)}]$ with $u_1^{(0)} = \lim_{\varepsilon \rightarrow 0} \varepsilon^{-1/2}u_1$, $u_2^{(0)} = \lim_{\varepsilon \rightarrow 0} \varepsilon^{-1/2}u_2$, and taking into account that the flow is irrotational in the two subdomains, we recover the Saint-Venant equations:

$$(7.2) \quad \begin{aligned} & \frac{\partial z^{(0)}}{\partial t} + \nabla \cdot (U^{(0)}z^{(0)}) = 0, \\ & \frac{\partial}{\partial t}U^{(0)} + U^{(0)} \cdot \nabla U^{(0)} + \frac{2\alpha}{\alpha+1}g\nabla z^{(0)} = 0 \\ & \text{with } U^{(0)} = ([u_1^{(0)}], [u_2^{(0)}]). \end{aligned}$$

However, we did not succeed in proving uniform convergence of the solution of the Rayleigh-Taylor problem when $\varepsilon \rightarrow 0$. Indeed, estimates (6.4), (6.5) and (6.55) do not lead to uniform estimates for $\tilde{V}_2 = \varepsilon^{-3/2}V_2$ in two dimensions or $\tilde{V}_3 = \varepsilon^{-3/2}V_3$ in three dimensions in terms of the Hölder norm of $\Omega^{(\varepsilon)} = \varepsilon^{-1/2}\Omega$. Uniform estimates have only been obtained in terms of the gradient of Ω . The Cauchy-Kowalewski Theorem concerning first order systems $\nabla\Omega$ must be considered as an additional unknown. But the equation for $\nabla\Omega$ introduces higher order derivatives such as $\nabla\nabla z$ (or y_{xx} in two dimensions) as additional variables inside a first order operator and the hierarchy can probably not be closed. Clearly, the difficulty originates from the necessity of considering the equation for the interface gradient (y_x or ∇z) to prove well-posedness of the Rayleigh-Taylor problem.

These two difficulties disappear for $\alpha = 1$ (water waves problem) in two dimensions when the approach of Ovsjannikov [3] and Kano and Nishida [4] is used. This method is based on a conformal mapping of the flow domain on a strip. It is, however, unclear how to extend this method, even in two dimensions to the Rayleigh-Taylor problem where the coupled dynamics of the two fluids must be considered.

Appendix. Large distance behaviour of the Green function of the equation:

$$(A.1) \quad f(\vec{x}) + \alpha \int_{R^2} \frac{2h}{(|\vec{x} - \vec{x}'|^2 + 4h^2)^{3/2}} f(\vec{x}') d\vec{x}' = S(\vec{x}).$$

The solution is obtained by taking the two-dimensional Fourier transform (F.T.) of (A.1) and noticing that the F.T. of the kernel is equal to e^{-2hk} . One obtains

$$(A.2) \quad f(\vec{x}) = \int \mathcal{G}(\vec{x}') S(\vec{x} - \vec{x}') d\vec{x}'$$

with $(x = |\vec{x}|)$

$$(A.3) \quad \mathcal{G}(\vec{x}) = \int_{R^2} \frac{e^{-i\vec{k} \cdot \vec{x}}}{1 + \alpha e^{-2kh}} d\vec{k} = \int_0^\infty \frac{k J_0(kx)}{1 + \alpha e^{-2kh}} dk.$$

The asymptotic behaviour of $\mathcal{G}(x)$ when $x \rightarrow \infty$ is obtained by using iteratively the following procedure:

(i) Make the substitution

$$(A.4) \quad J_0(kx) = \frac{1}{x} \frac{d}{dk} (kJ_1(kx)).$$

(ii) Integrate by parts.

(iii) Make the substitution

$$(A.5) \quad J_1(kx) = -\frac{1}{x} \frac{d}{dk} J_0(kx).$$

Defining

$$(A.6) \quad f(k) = \frac{2h}{1 + \alpha e^{-2hk}}$$

and

$$(A.7) \quad g(k) = \frac{df}{dk} = \frac{4\alpha h^2 e^{-2hk}}{(1 + \alpha e^{-2hk})^2}$$

we have

$$(A.8) \quad \begin{aligned} \int_0^\infty f(k) k J_0(kx) dk &= \frac{1}{x} \int_0^\infty f(k) \frac{d}{dk} (kJ_1(kx)) dk \\ &= \frac{1}{x} \int_0^\infty g(k) k J_1(kx) dk \\ &= \frac{1}{x^2} \int_0^\infty kg(k) \frac{d}{dk} J_0(kx) dk \\ (A.9) \quad &= -\frac{1}{x^2} \int_0^\infty \frac{d}{dk} (kg(k)) J_0(kx) dk \\ &= -\frac{1}{x^3} \int_0^\infty \frac{1}{k} \frac{d}{dk} (kg(k)) \frac{d}{dk} (kJ_1(kx)) dk \\ &= \frac{1}{x^3} \int_0^\infty \frac{d}{dk} \left(\frac{1}{k} \frac{d}{dk} (kg(k)) \right) k J_1(kx) dk \\ &= \frac{1}{x^3} \int_0^\infty F\left(\frac{\lambda}{x}\right) J_1(\lambda) \frac{d\lambda}{\lambda} \end{aligned}$$

with

$$(A.10) \quad F\left(\frac{\lambda}{x}\right) = \lambda^2 \frac{d}{d\lambda} \left\{ \frac{1}{\lambda} \frac{d}{d\lambda} \left(\lambda g\left(\frac{\lambda}{x}\right) \right) \right\}$$

and

$$(A.11) \quad g(\lambda/x) = \alpha h e^{-2h(\lambda/x)} / (1 + \alpha e^{-2h(\lambda/x)^2}).$$

$F(\lambda/x)$ is uniformly bounded in x and λ ; $J_1(\lambda) \sim \lambda$ when $\lambda \rightarrow 0$ and $J_1(\lambda) \sim \lambda^{-1/2}$ when $\lambda \rightarrow \infty$. It follows that the integral in the last term of (A.9) is bounded. As a consequence, $\mathcal{G}(x) \in L^1(R^2)$.

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